

# **Structured Electronic Design**

EE4109

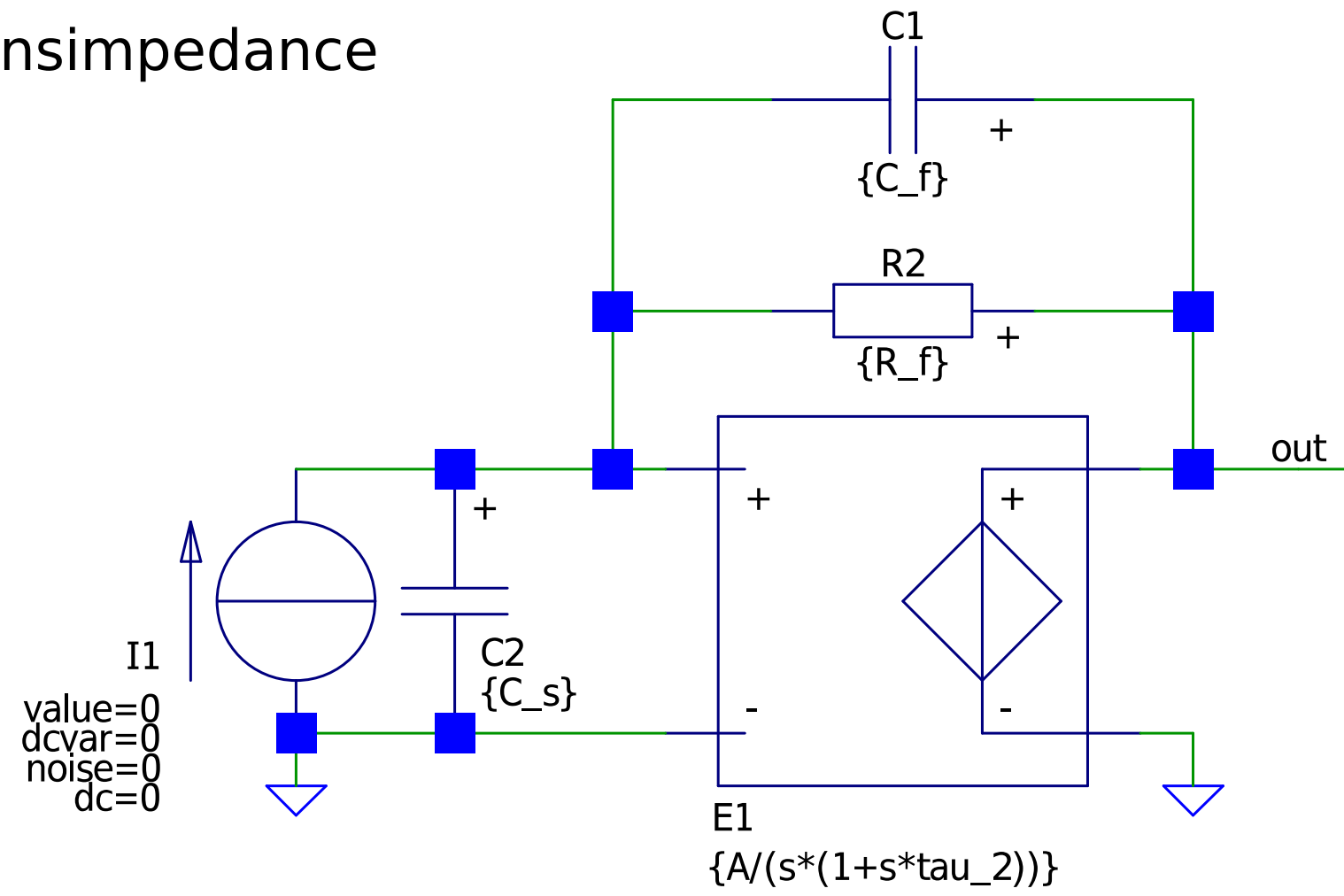
Bandwidth limitation  
with phantom zeros

*Anton J.M. Montagne*

# Phantom zero compensation

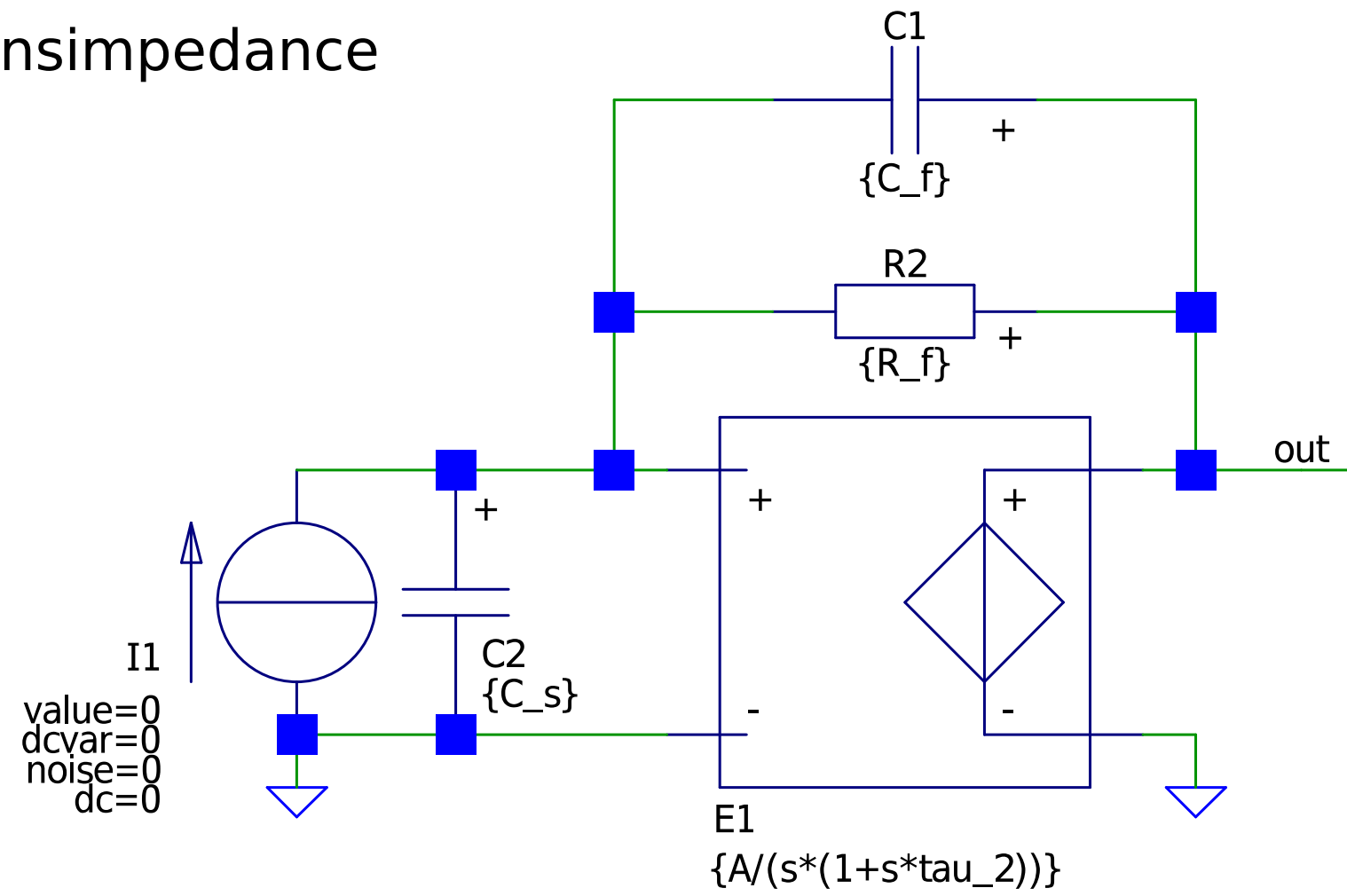
# Phantom zero compensation

Transimpedance



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$$C_f = 0$$

$$\tau_2 = 0$$

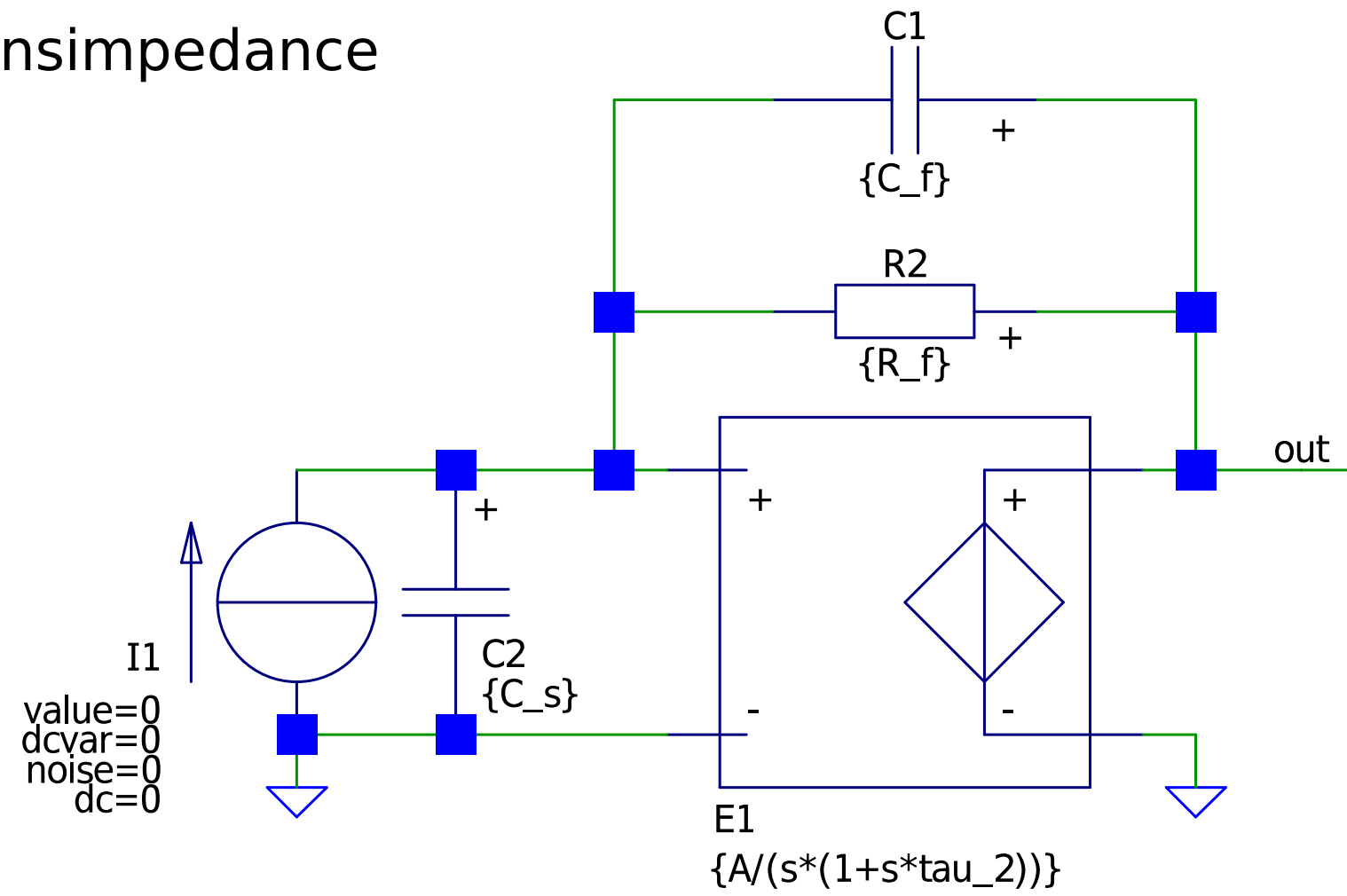
$$A = -10 \cdot 10^6$$

$$R_f = 10 \cdot 10^3$$

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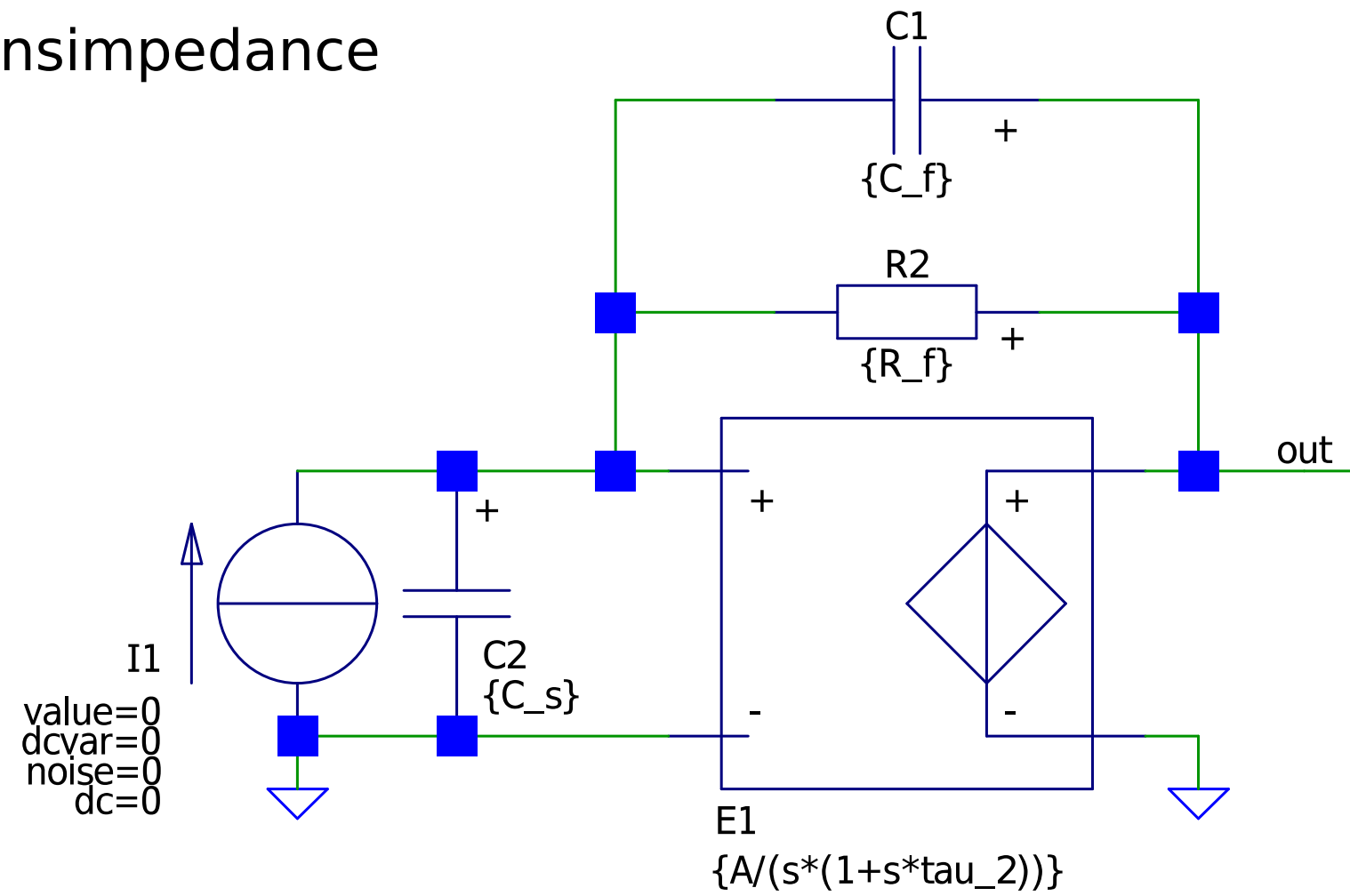
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Loop gain reference: E1

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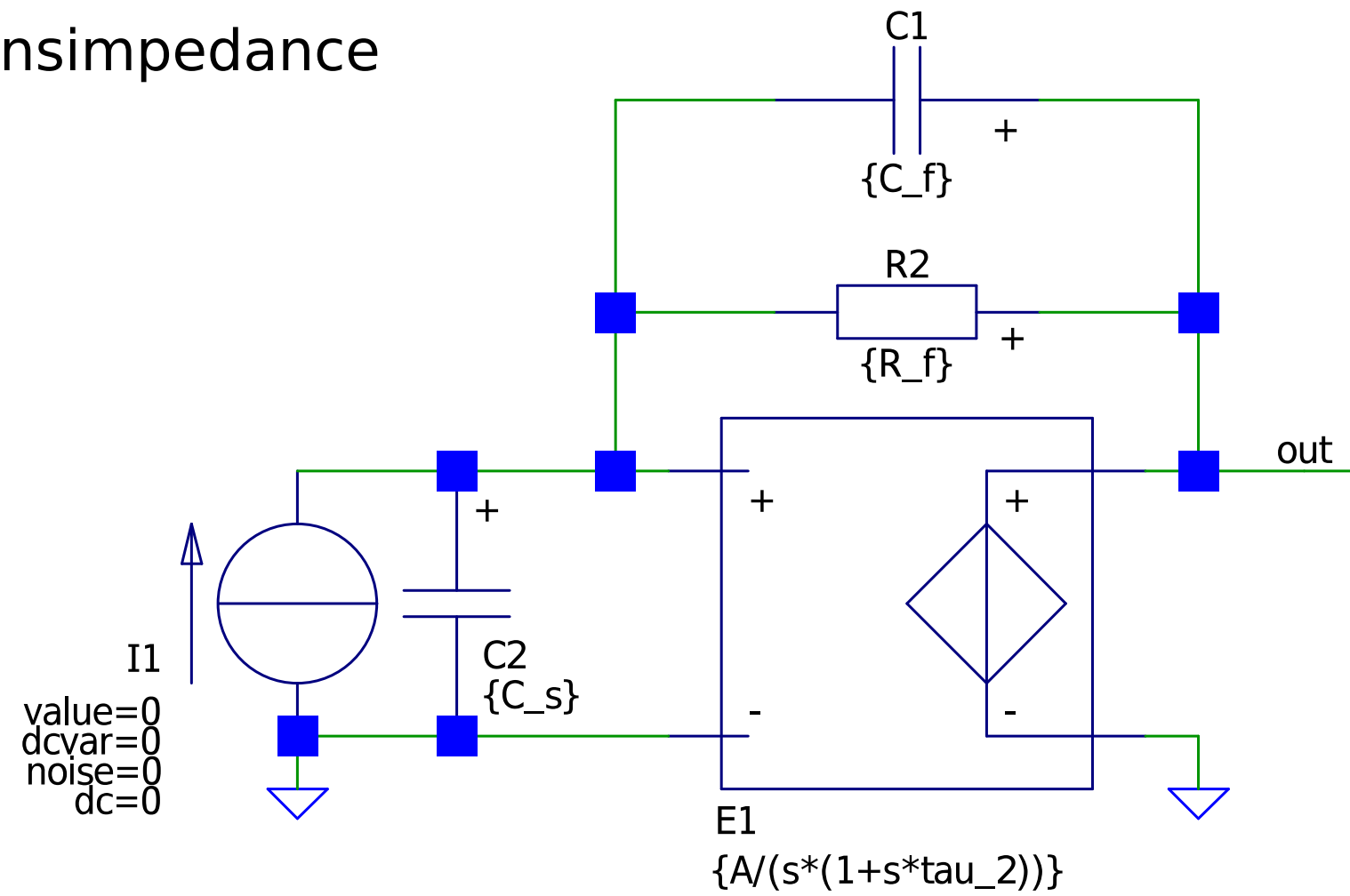
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How many loop gain poles?

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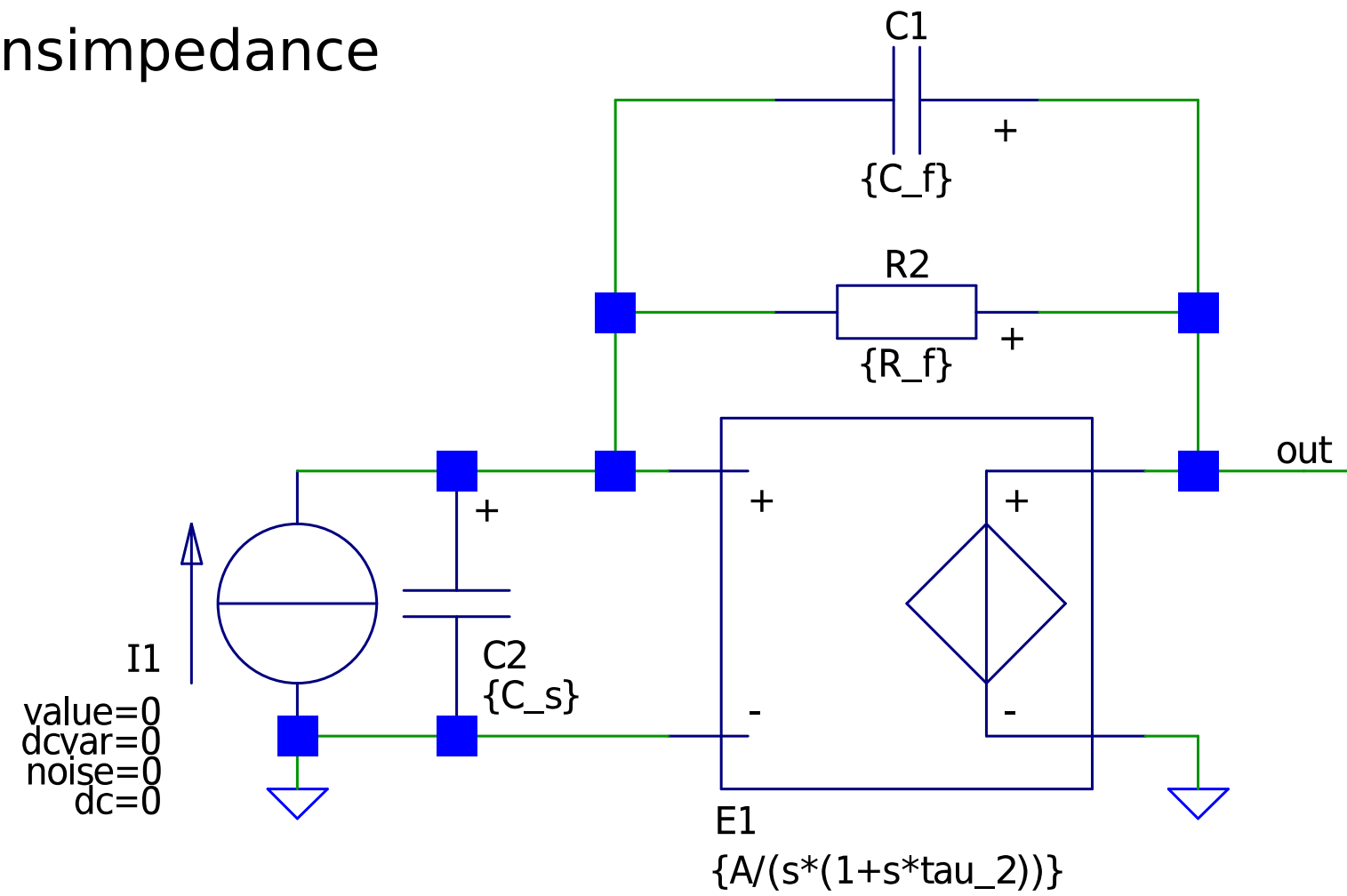
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$$p_1 = 0, p_2 = -\frac{1}{2\pi R_f (C_s + C_f)} = -53\text{kHz}$$

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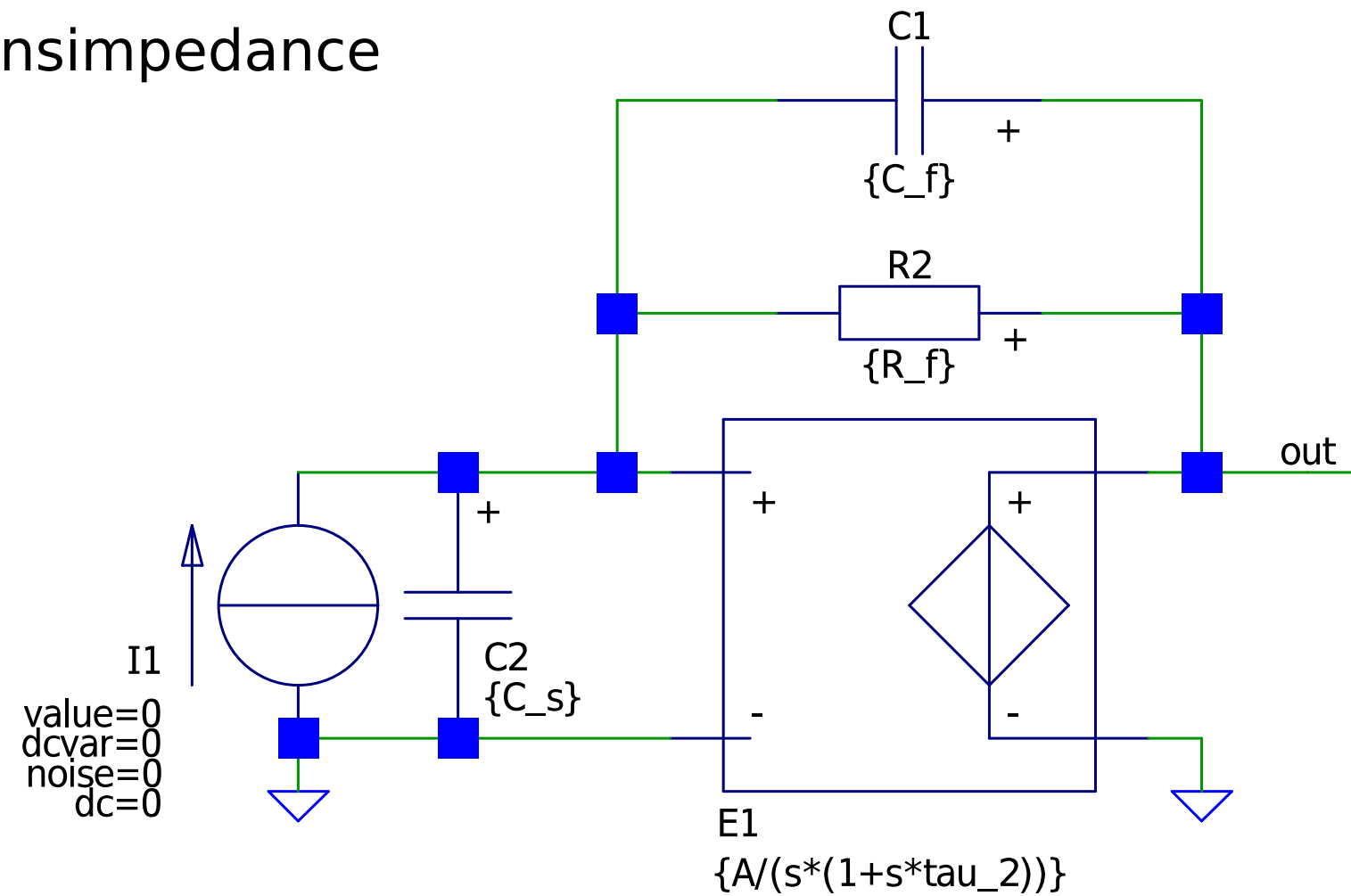
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$$B_f = \frac{1}{2\pi} \sqrt{\left| \frac{A}{R_f C_s} \right|} = 410\text{kHz}$$

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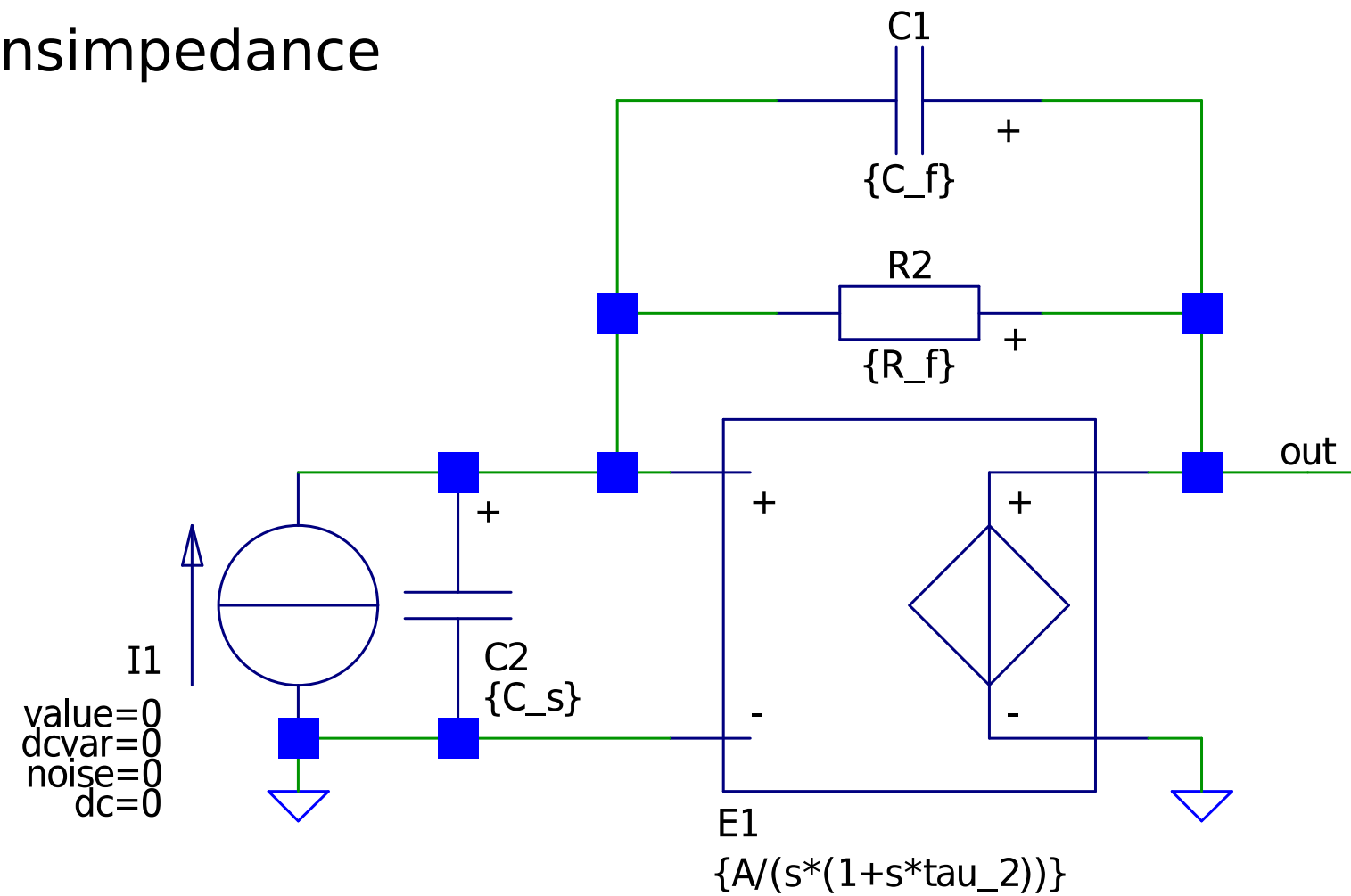
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Is phantom-zero compensation for MFM possible?

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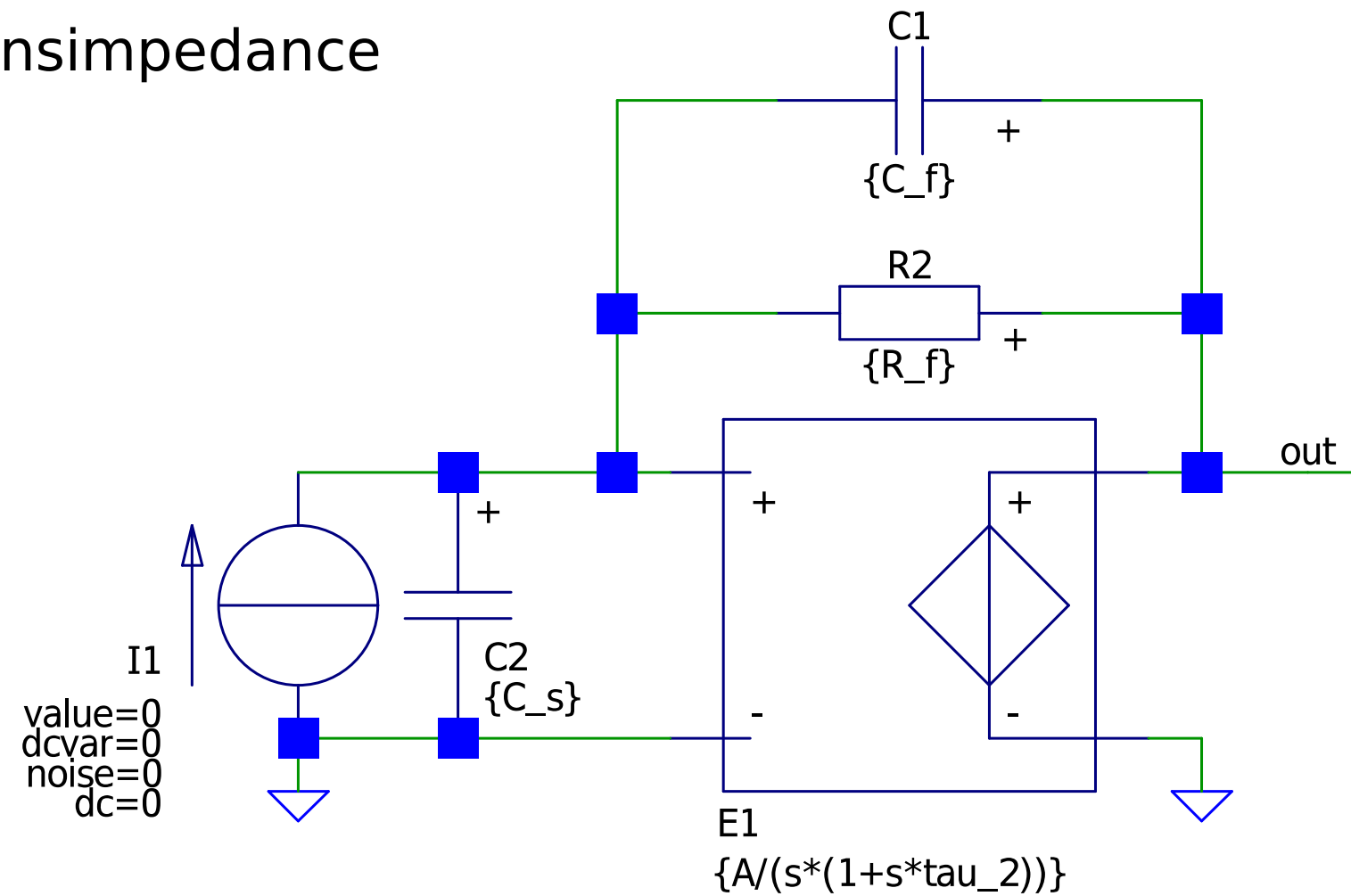
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Is phantom-zero compensation for MFM possible?

$$C_f = \frac{\sqrt{2} B_f + p_1 + p_2}{2\pi B_f R_f^2} = 50\text{pF}$$

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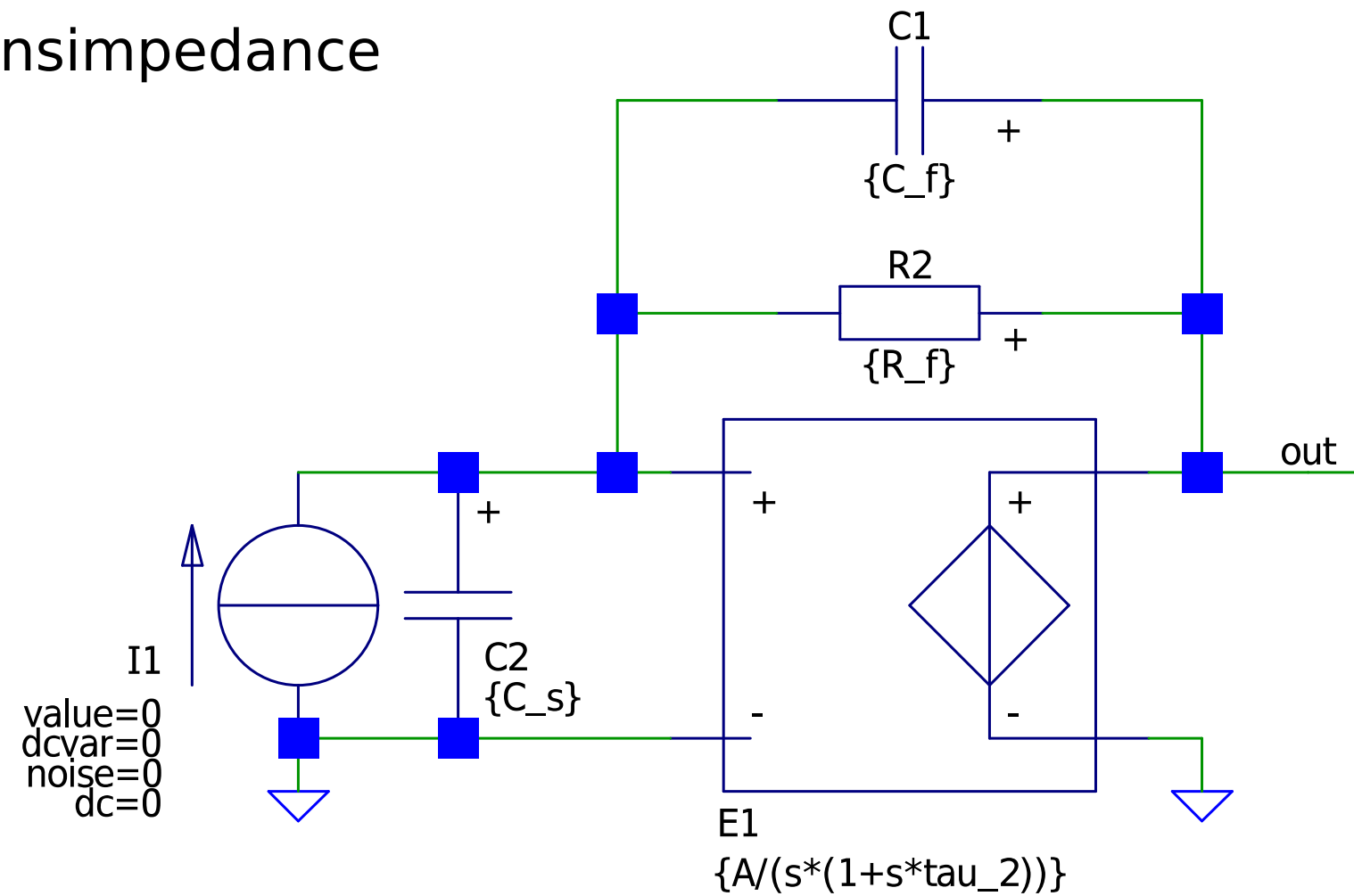
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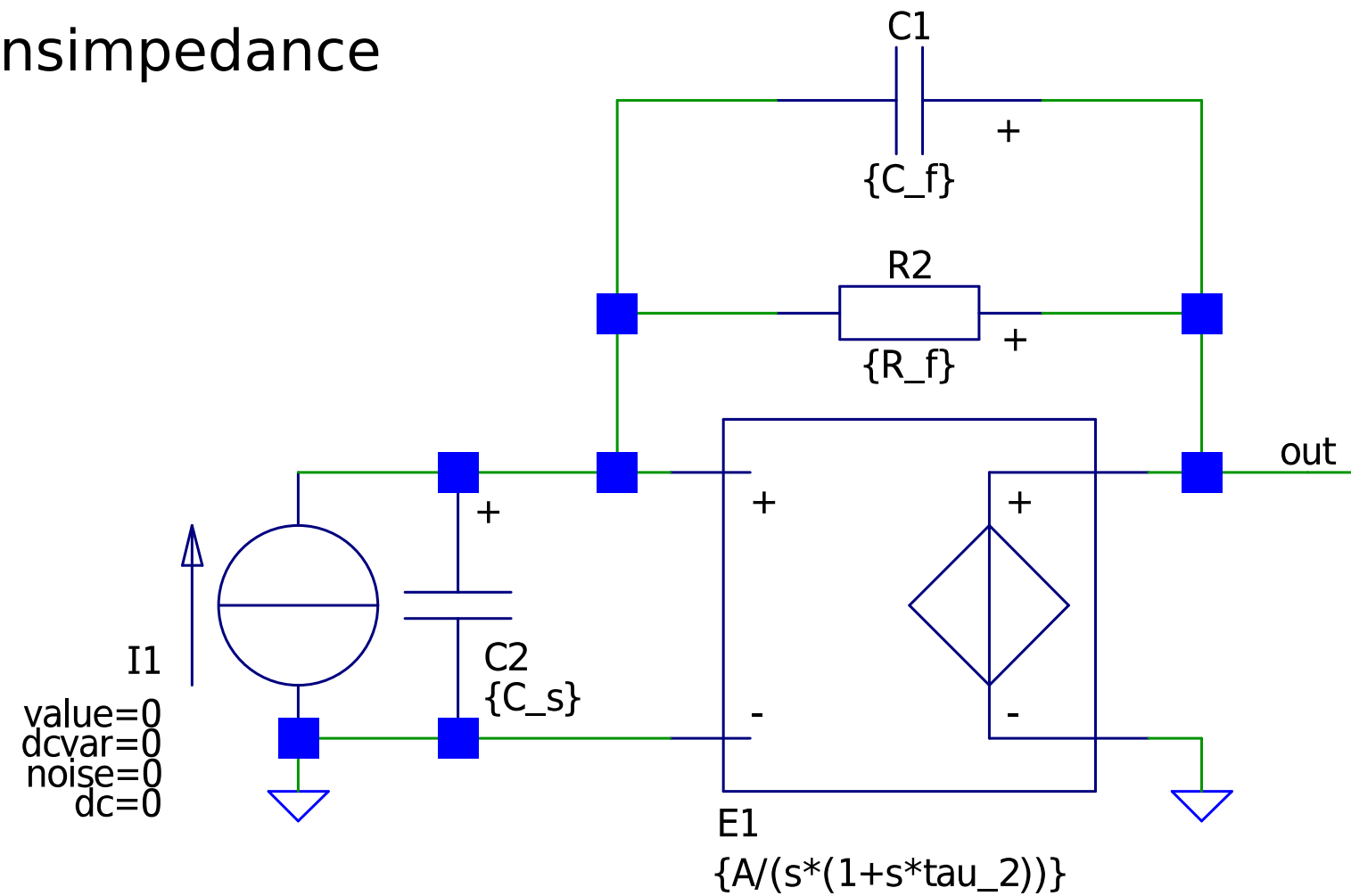
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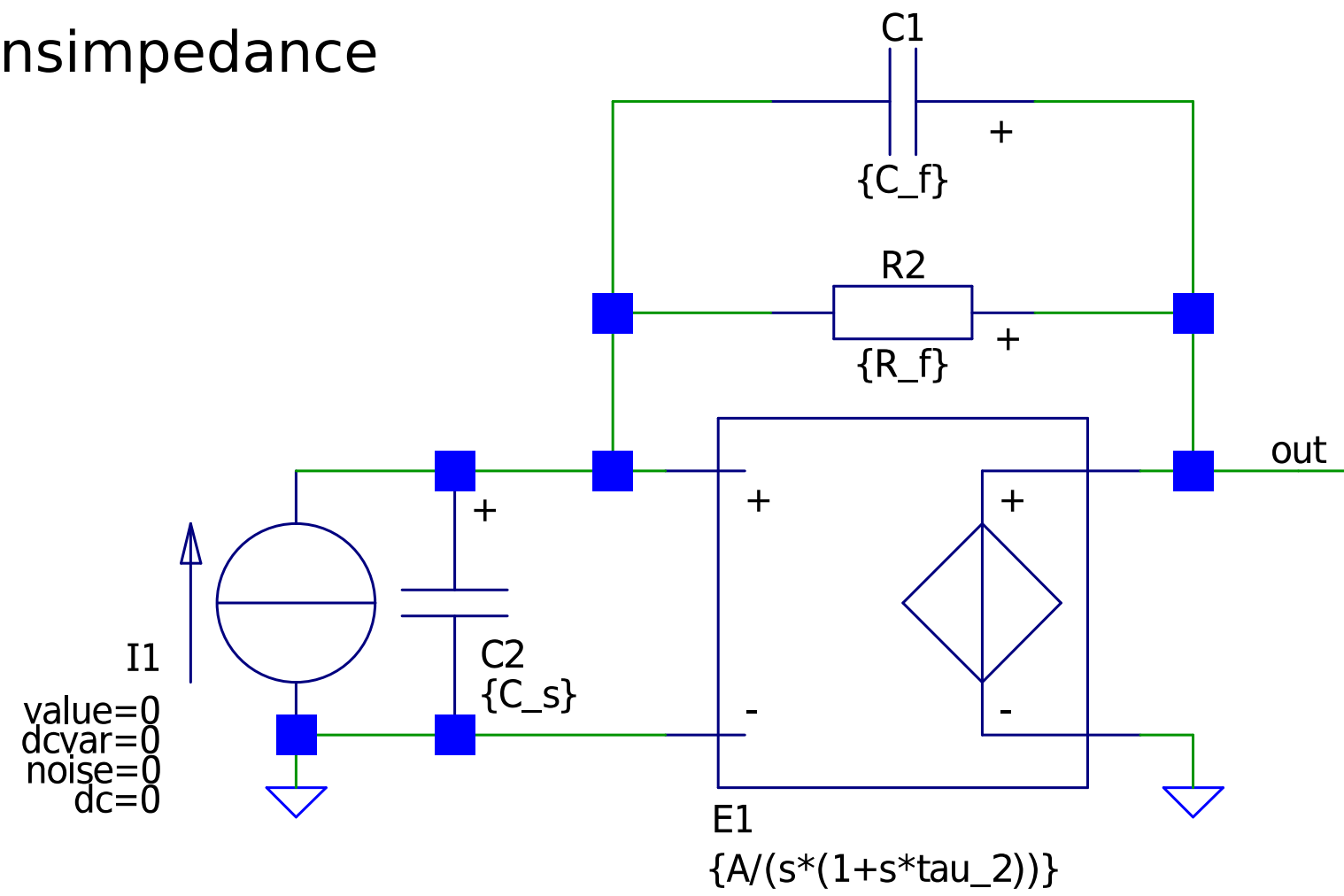
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# Phantom zero bandwidth limitation

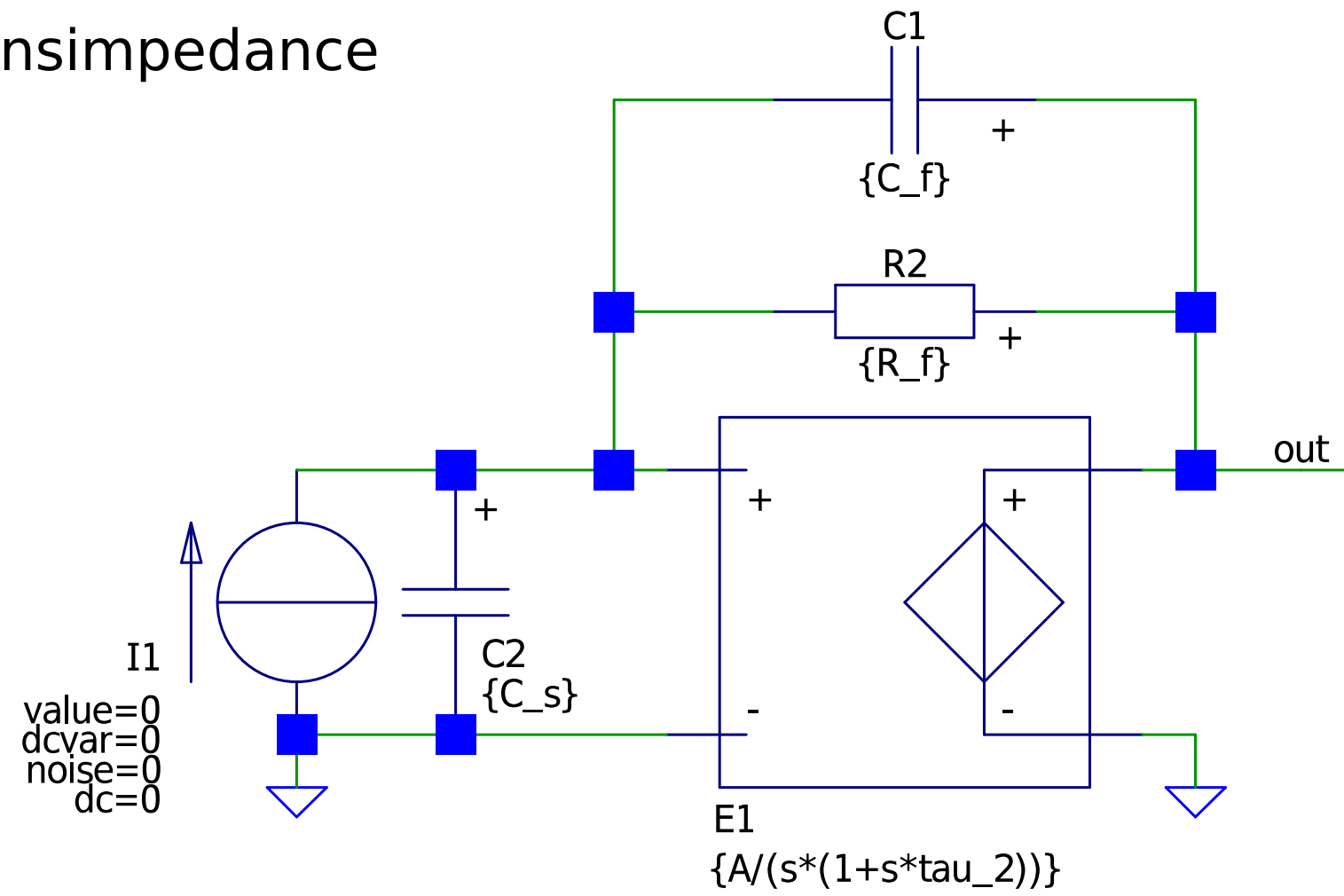
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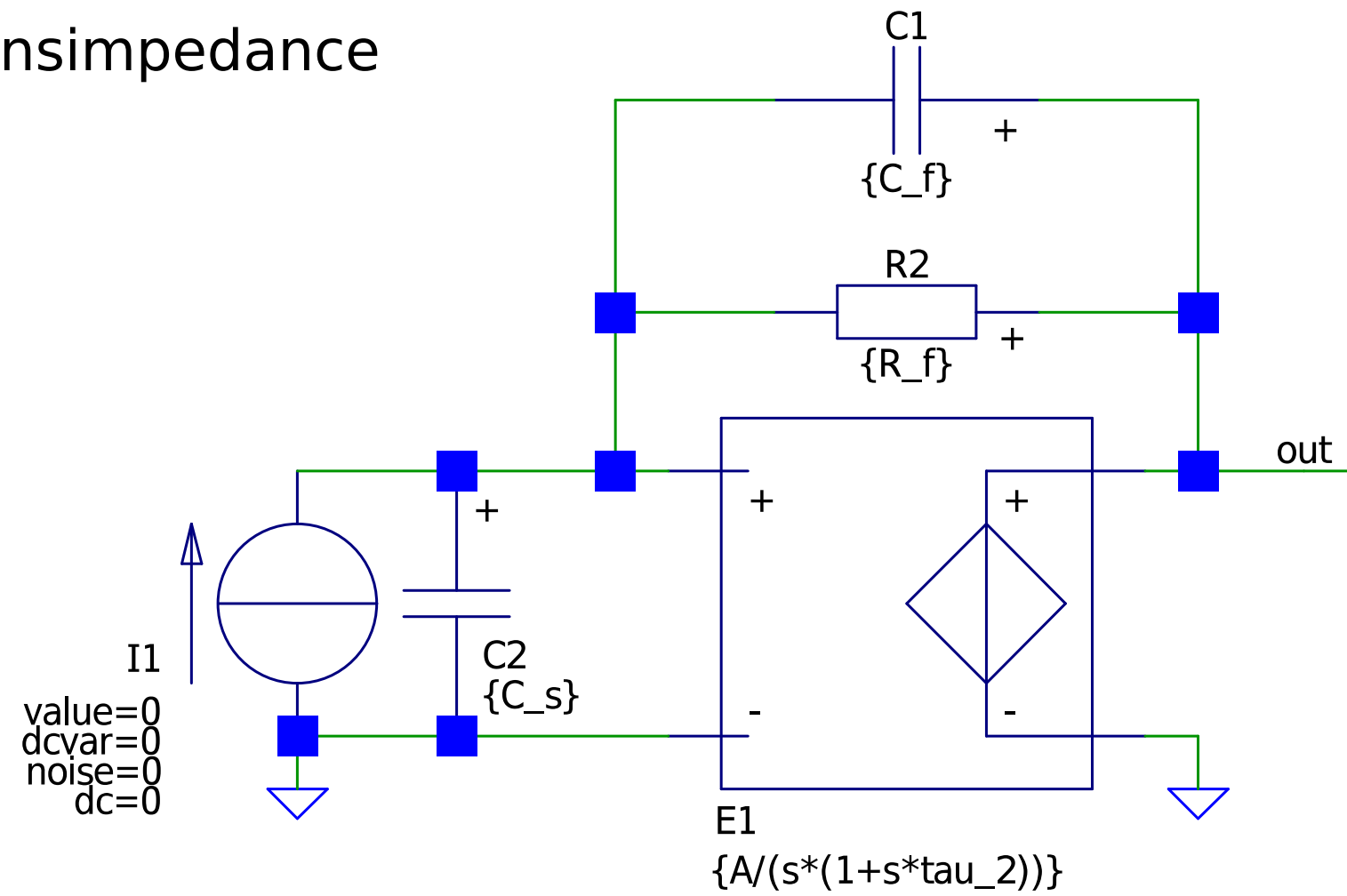
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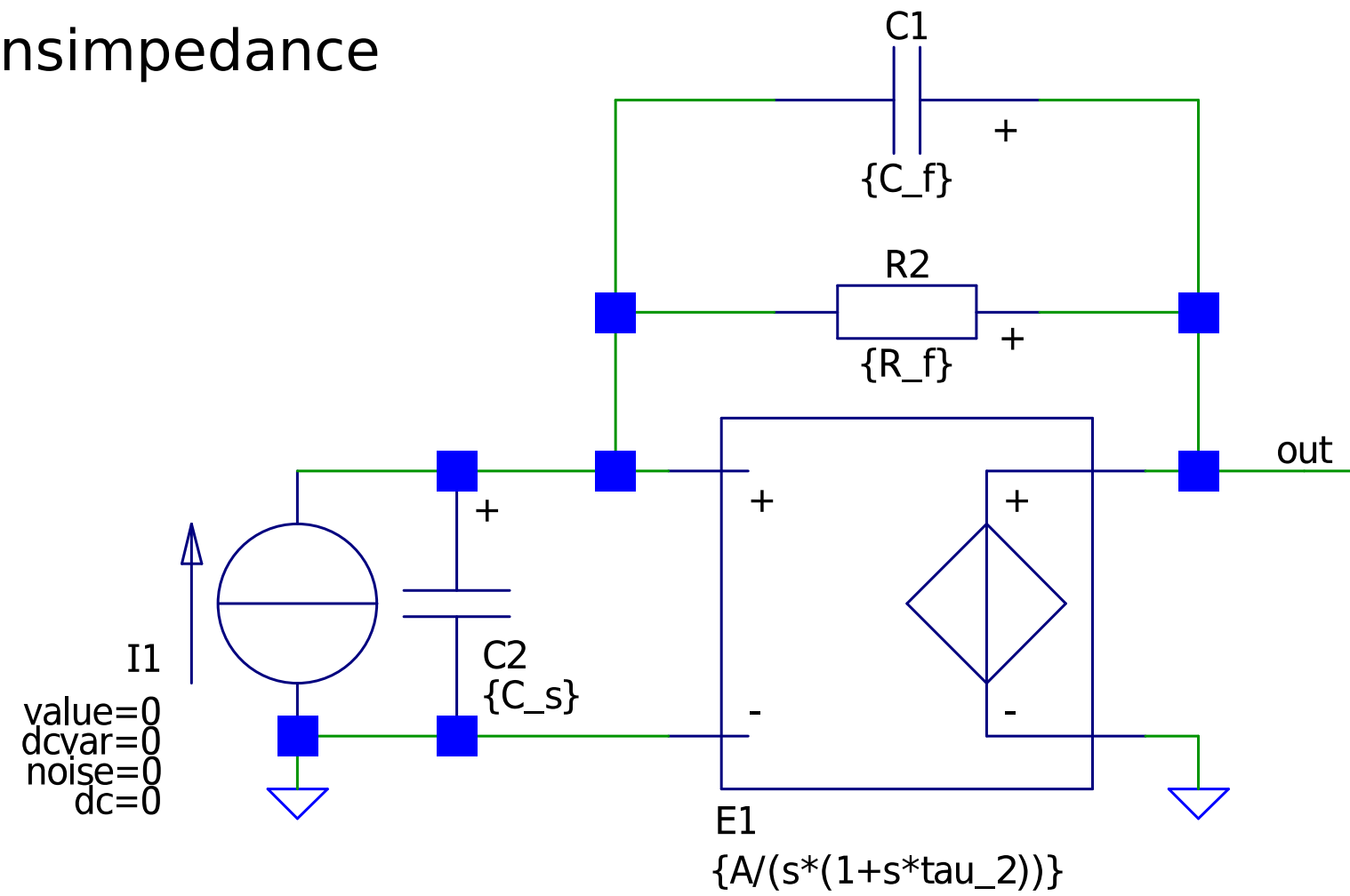
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$$\frac{V_{out}}{I_1} = A_f \infty \frac{-L}{1-L}$$

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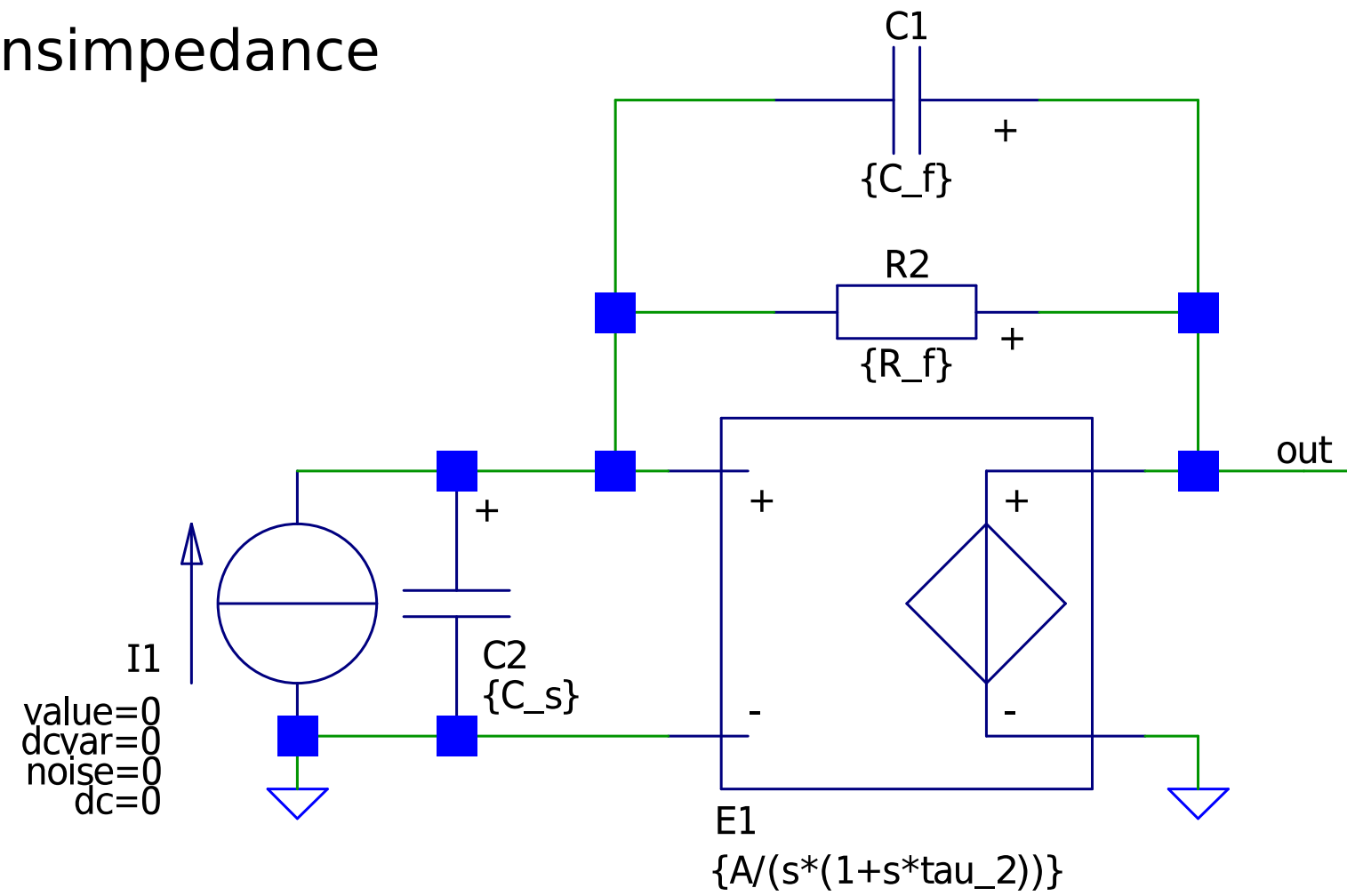
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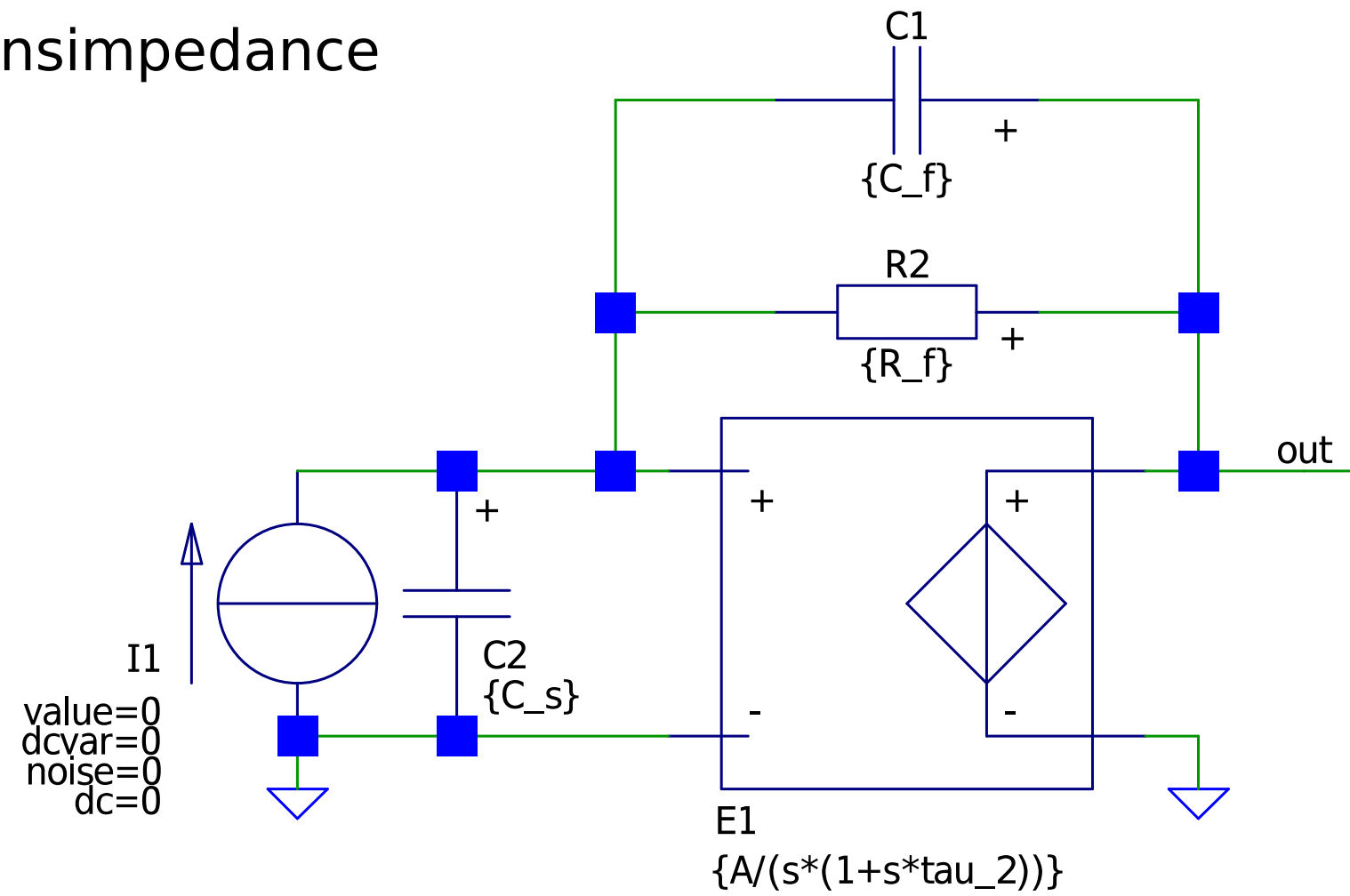
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Phantom zero:

Pole in asymptotic-gain

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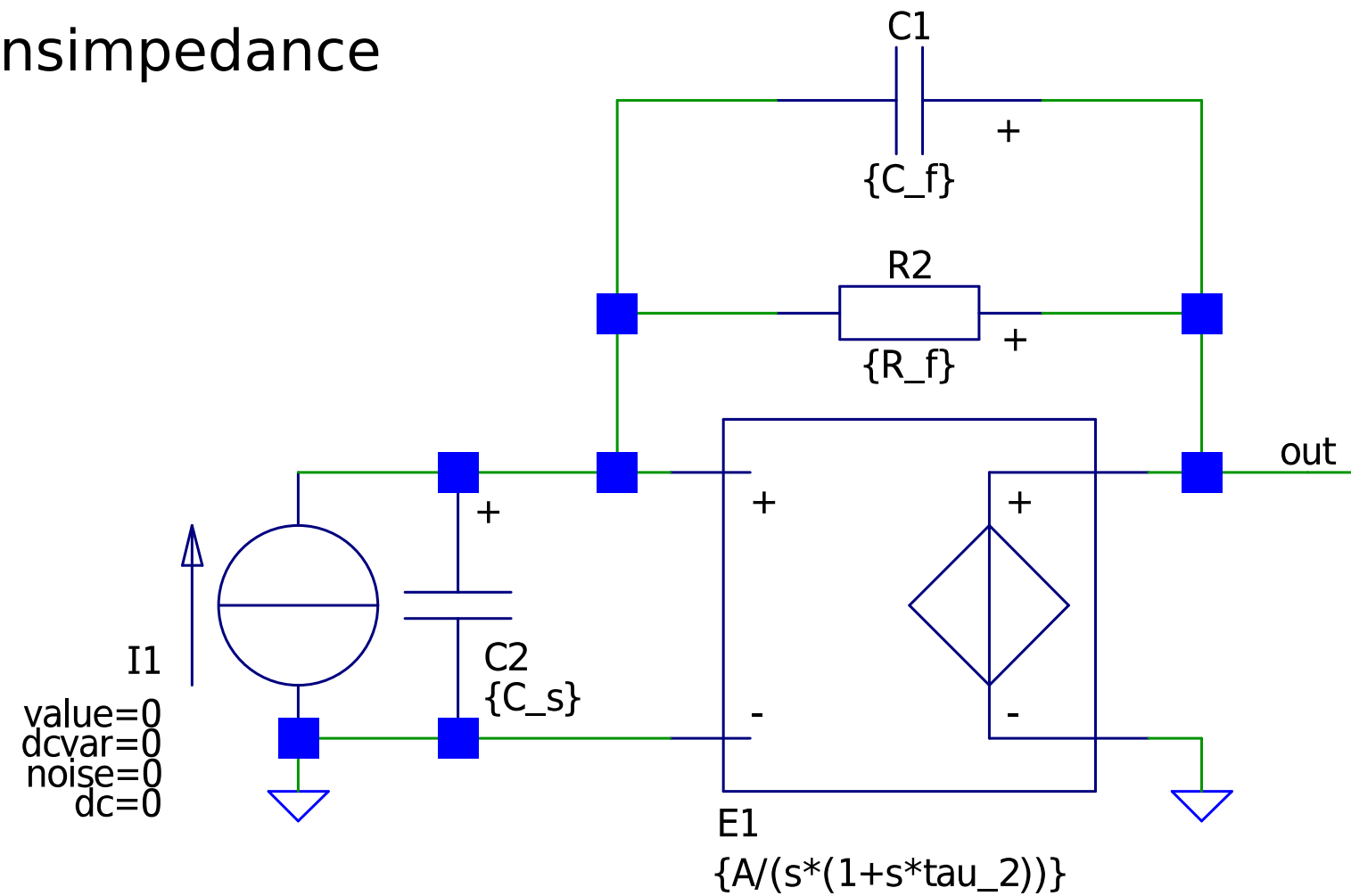
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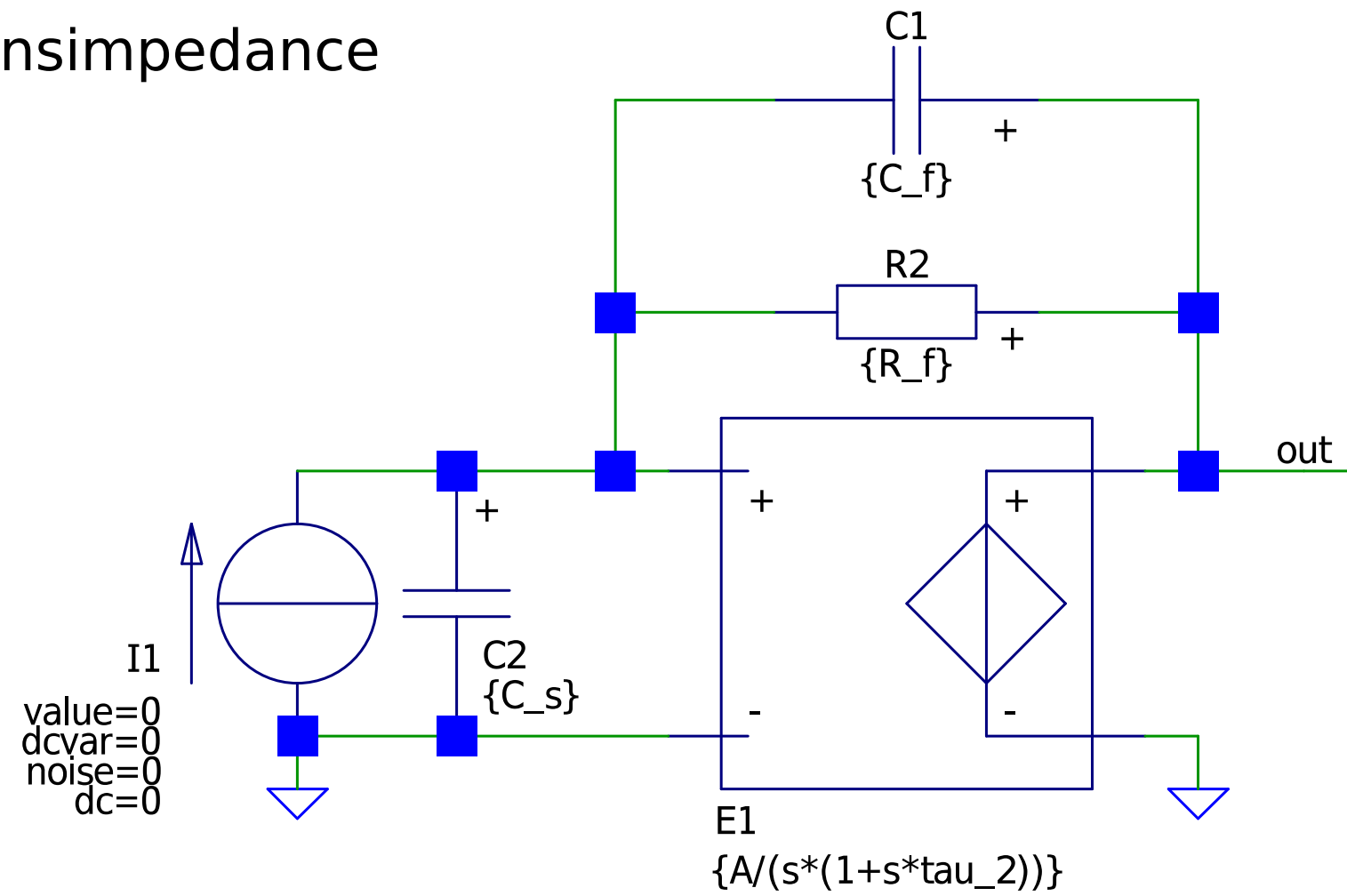
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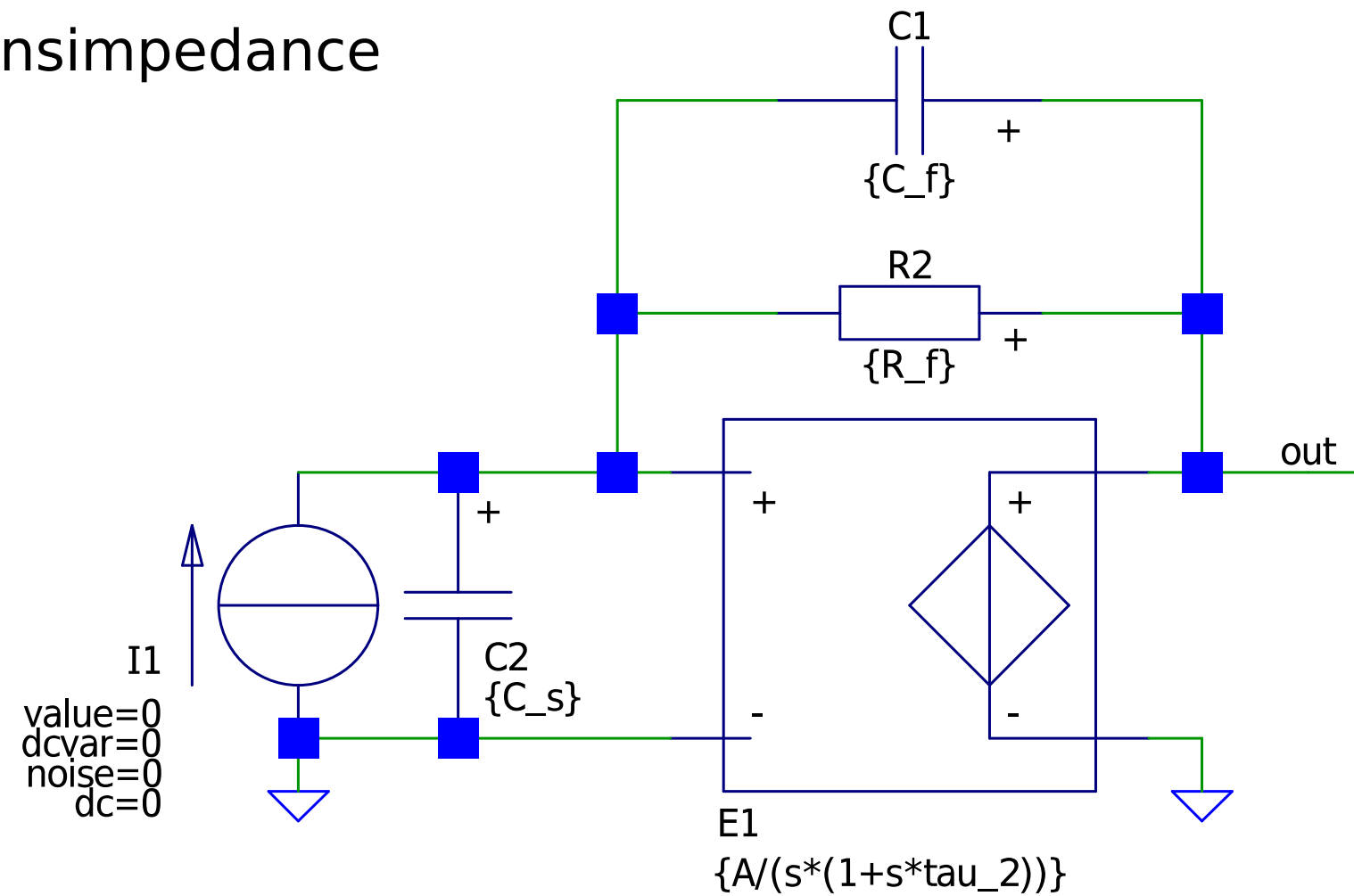
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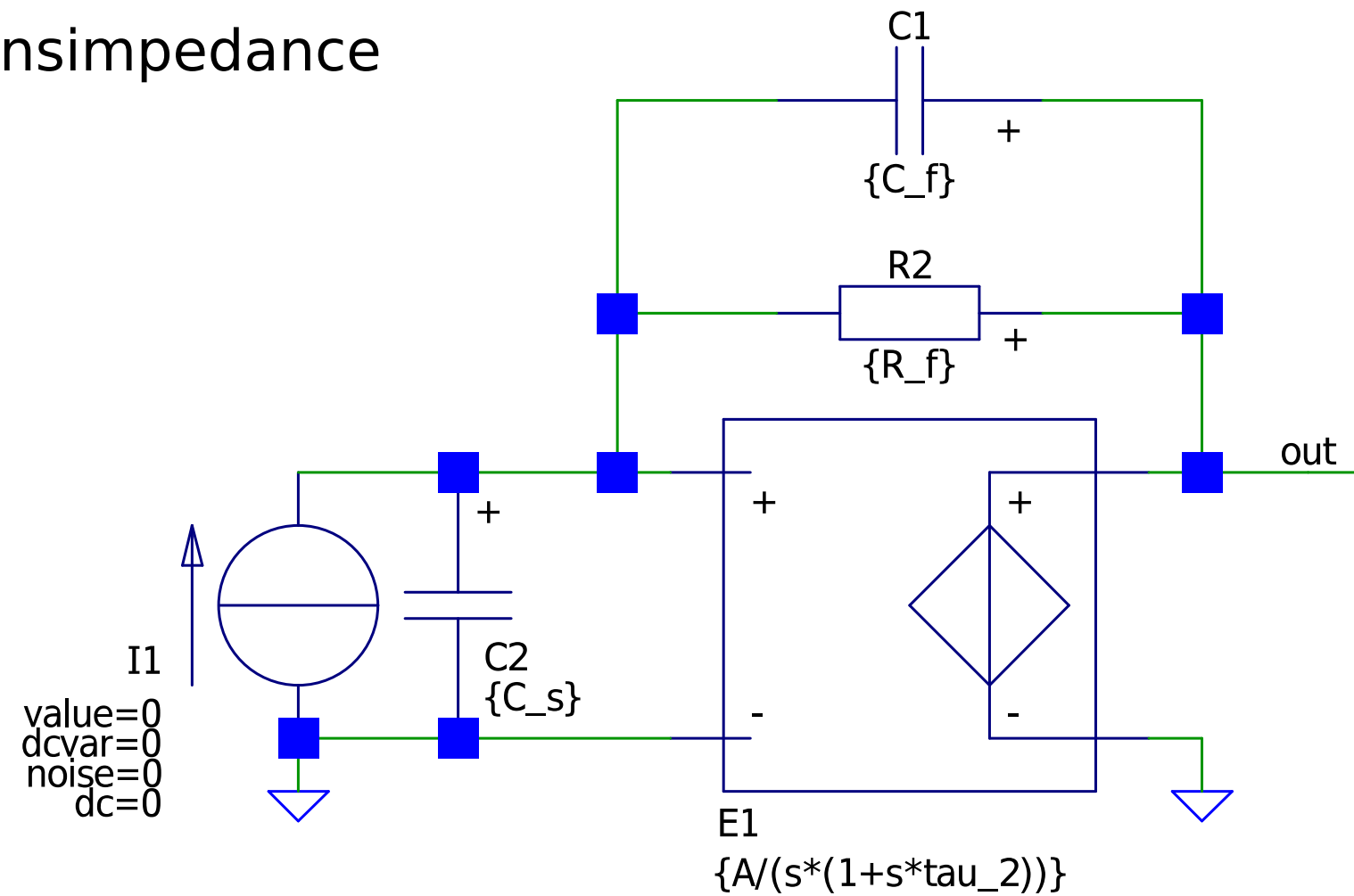
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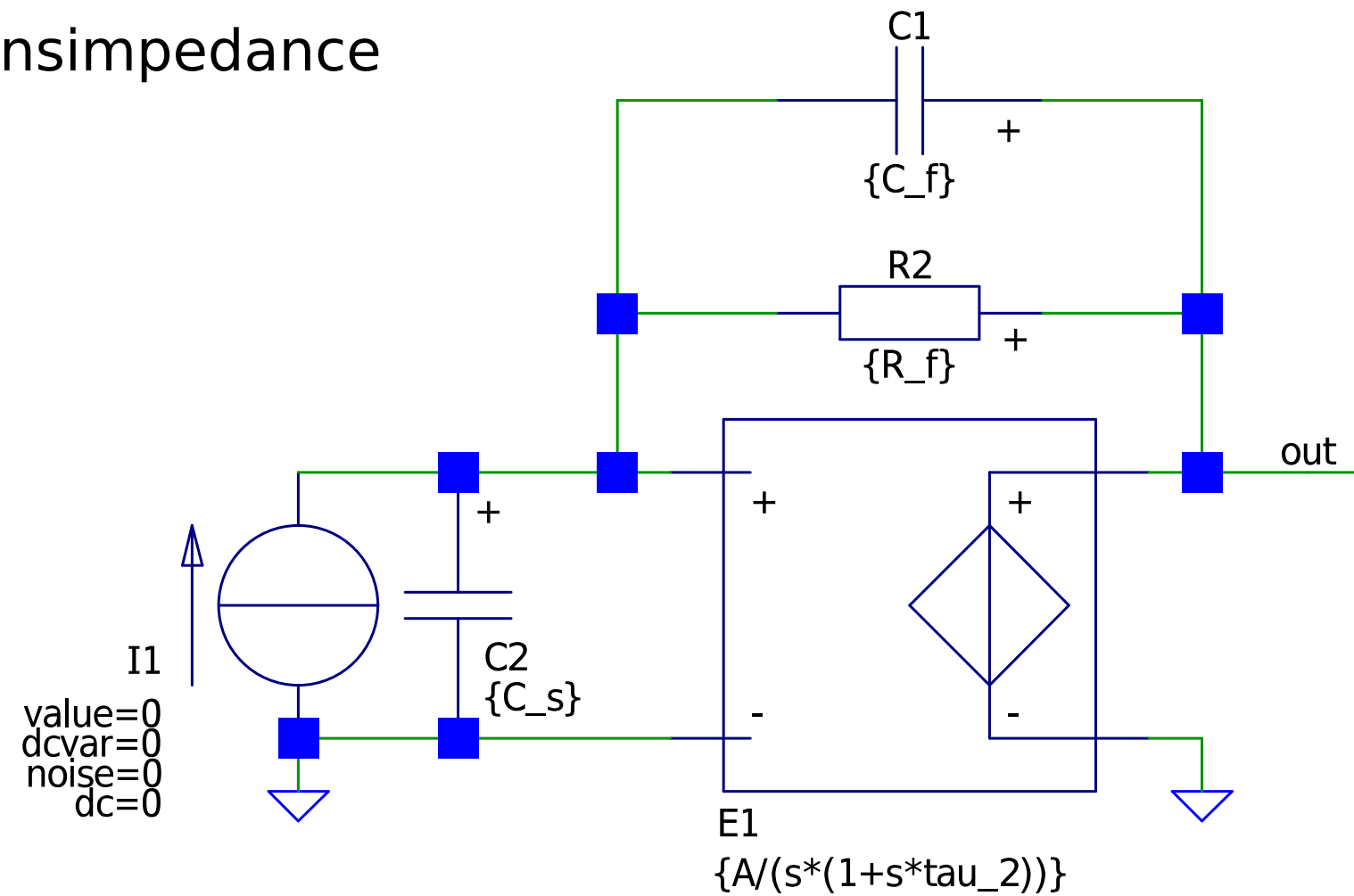
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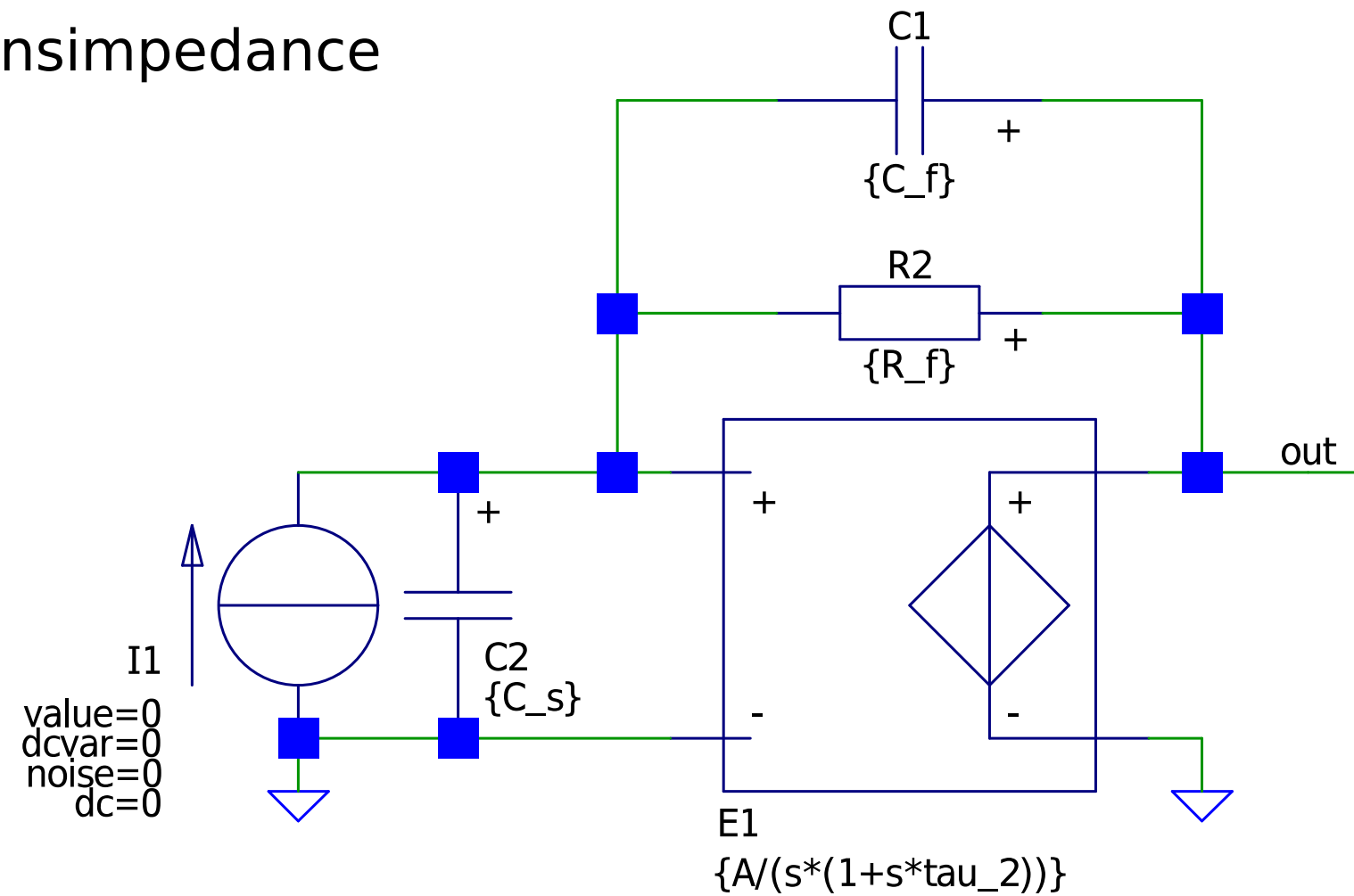
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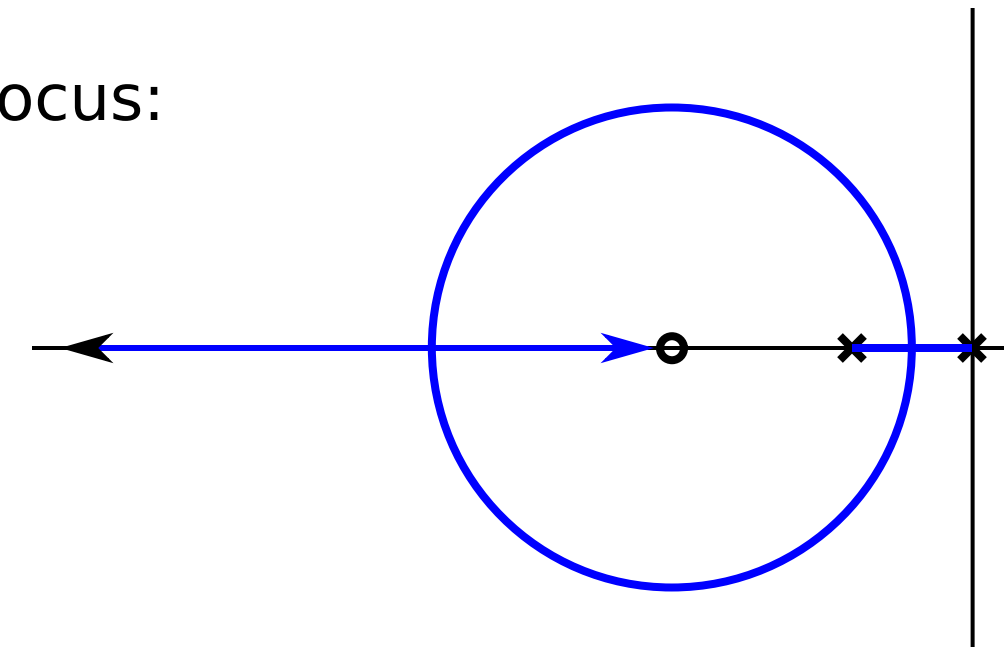


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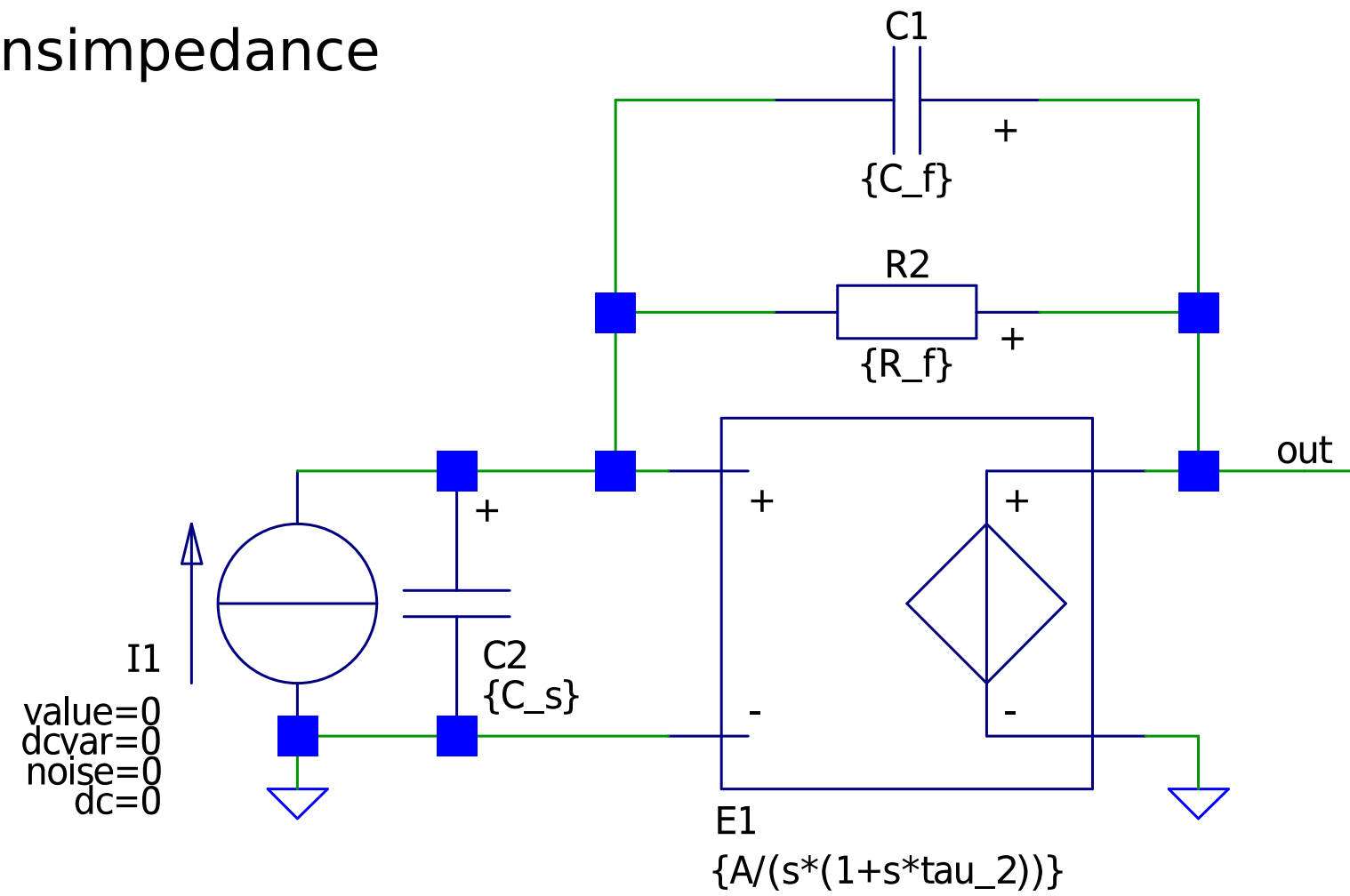
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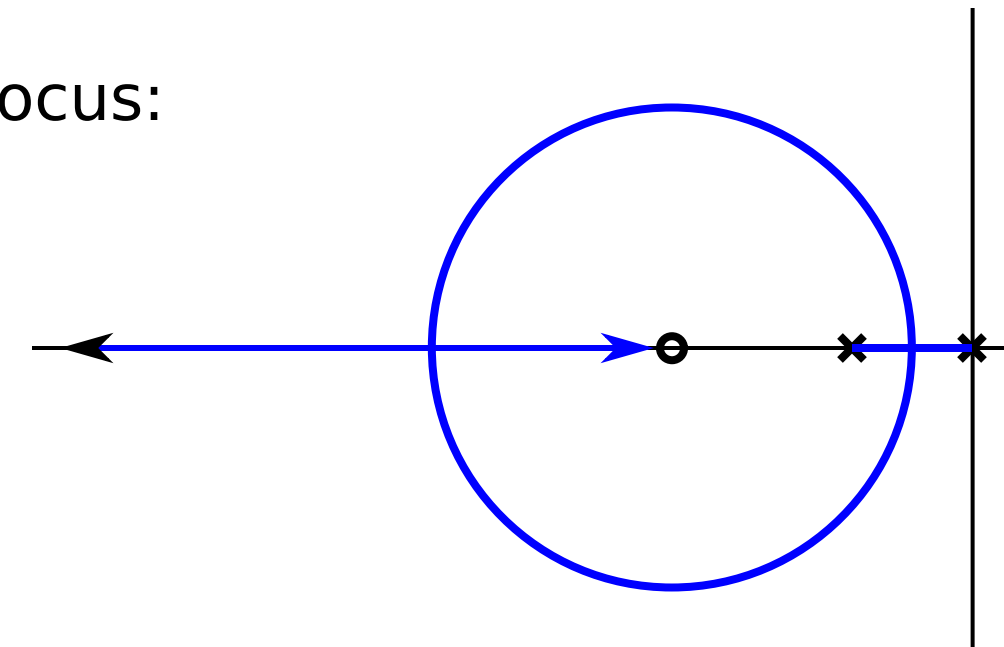


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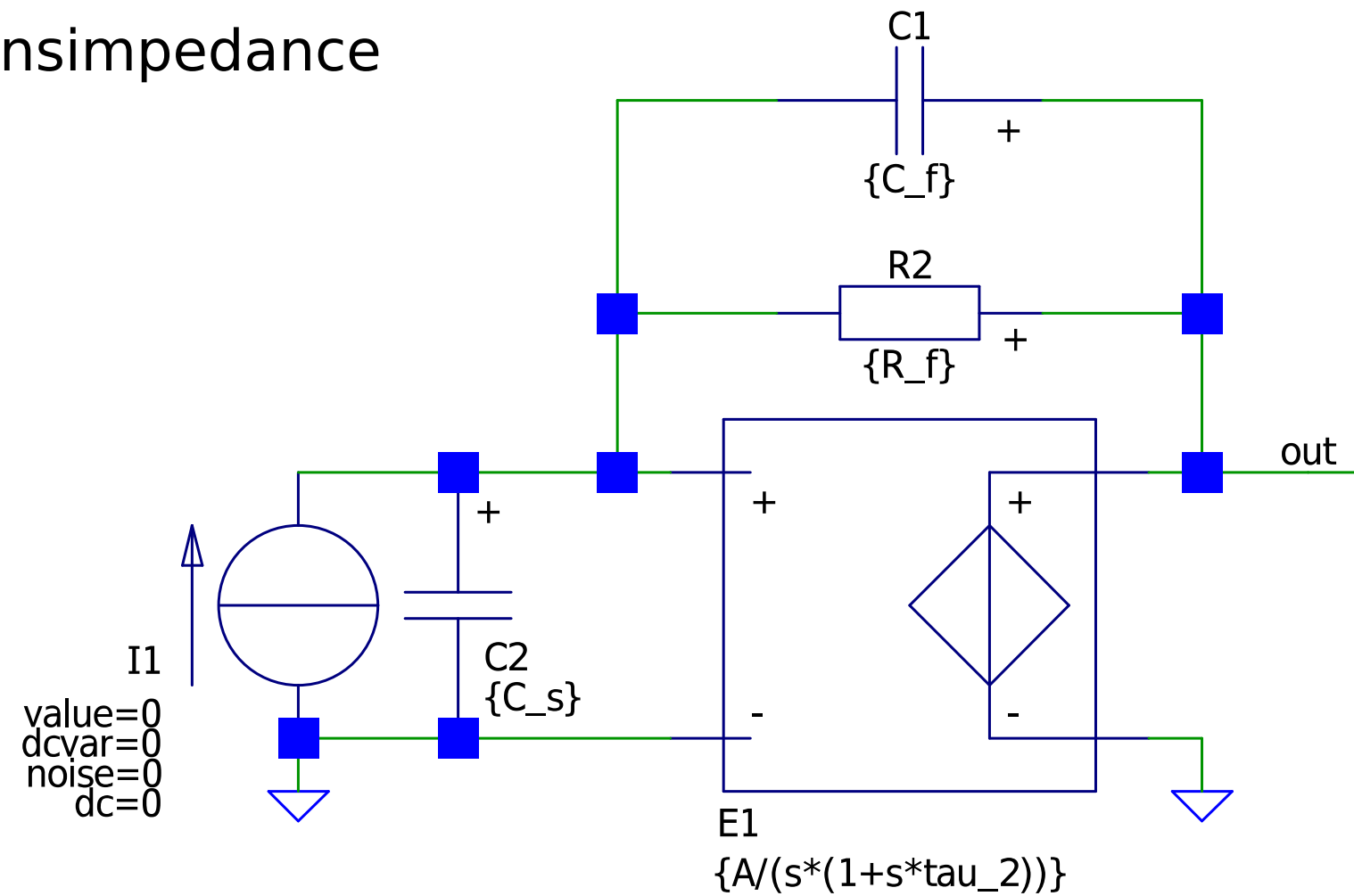
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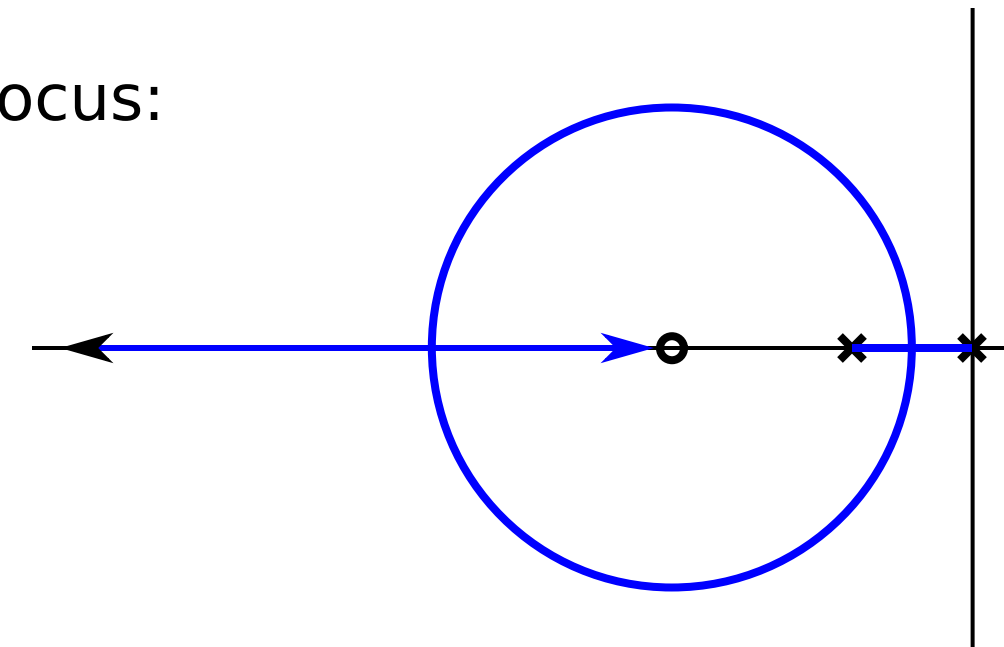


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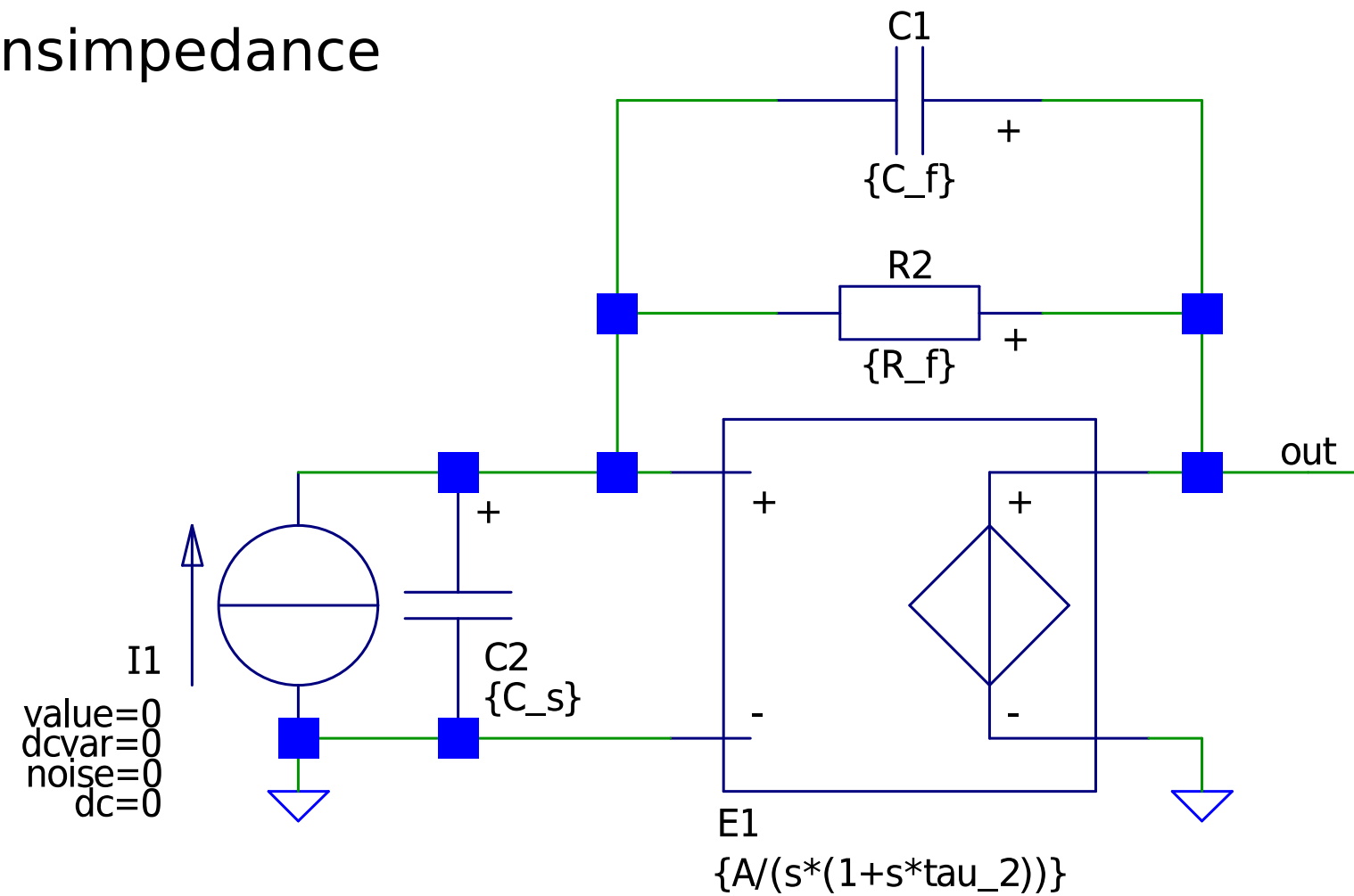
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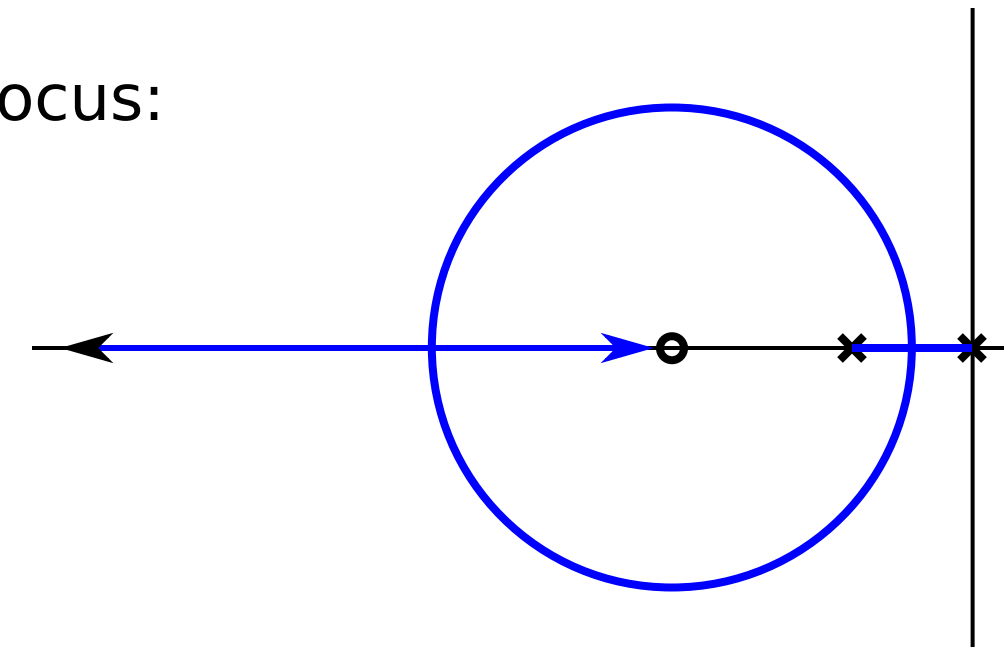


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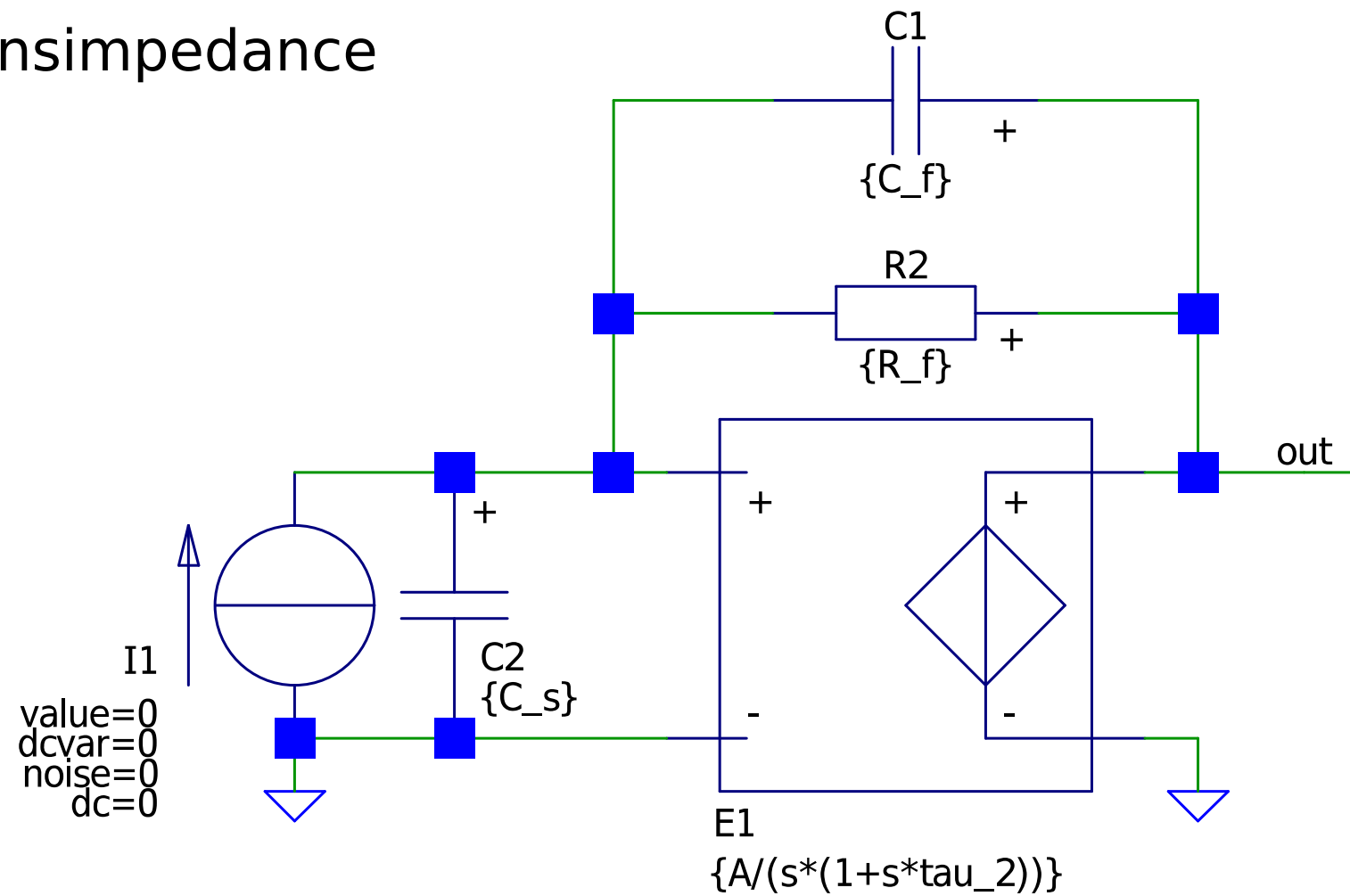
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The servo bandwidth increases with the loop gain

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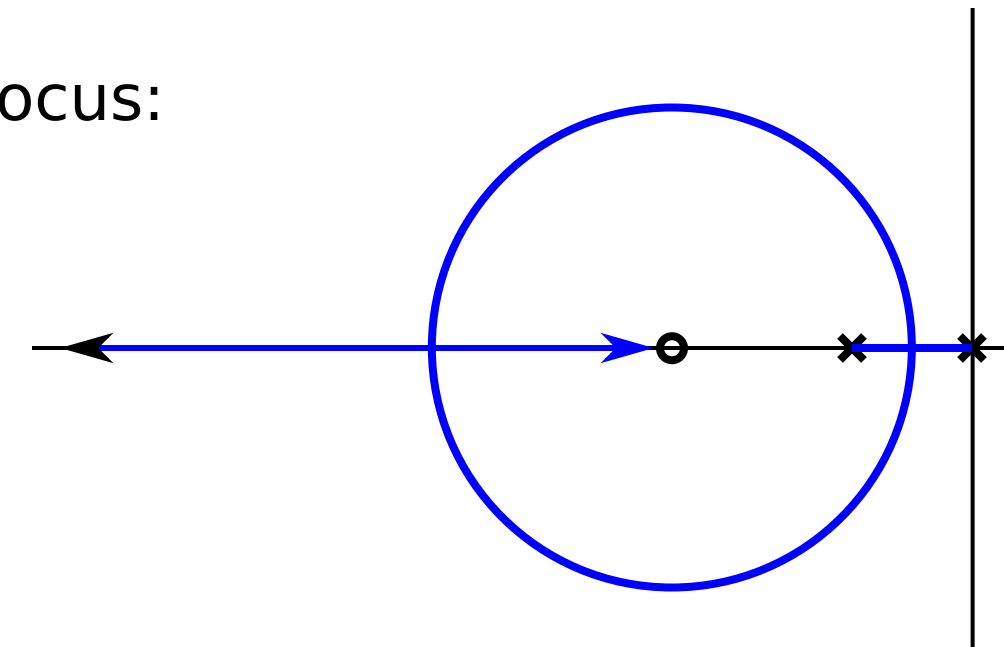


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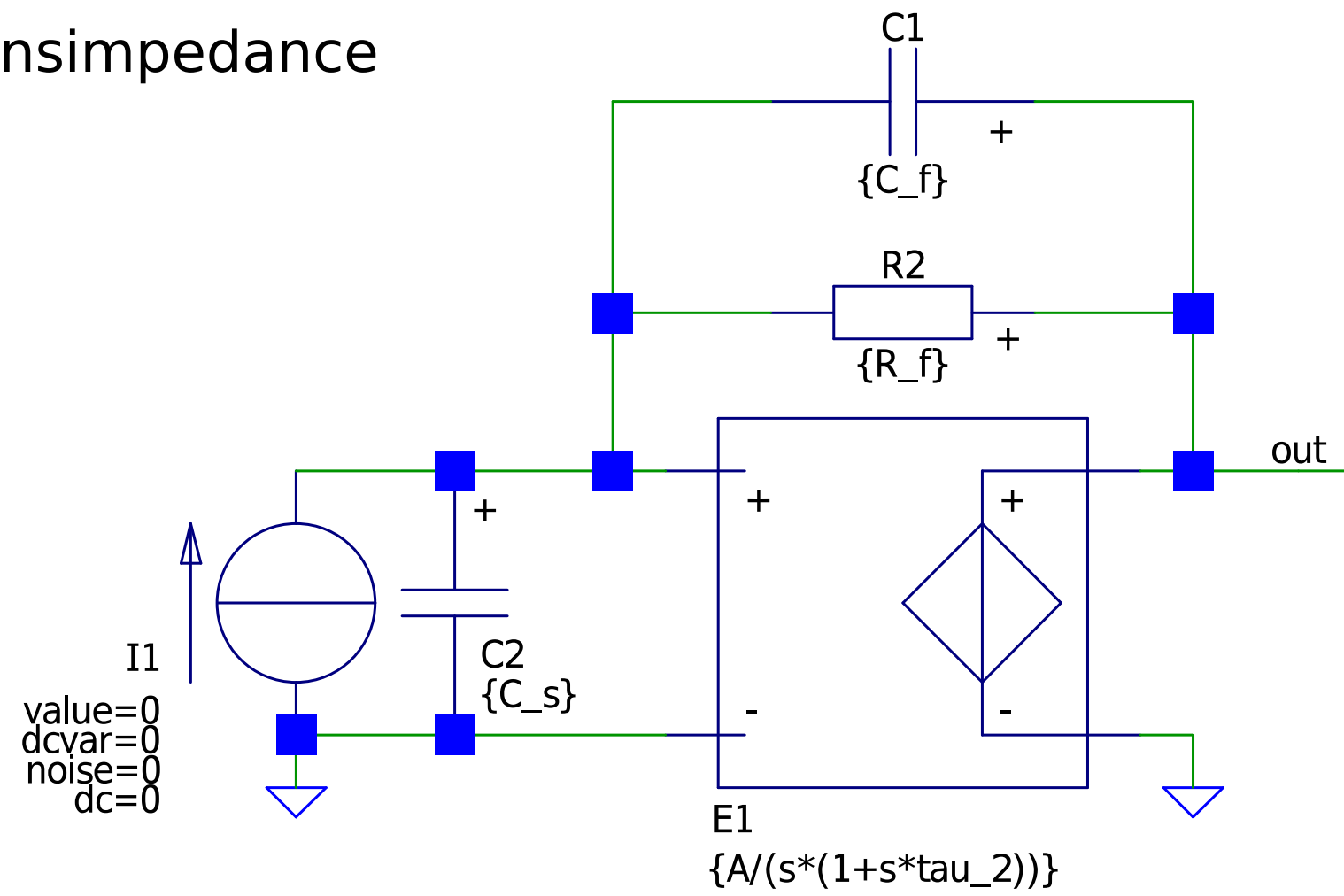
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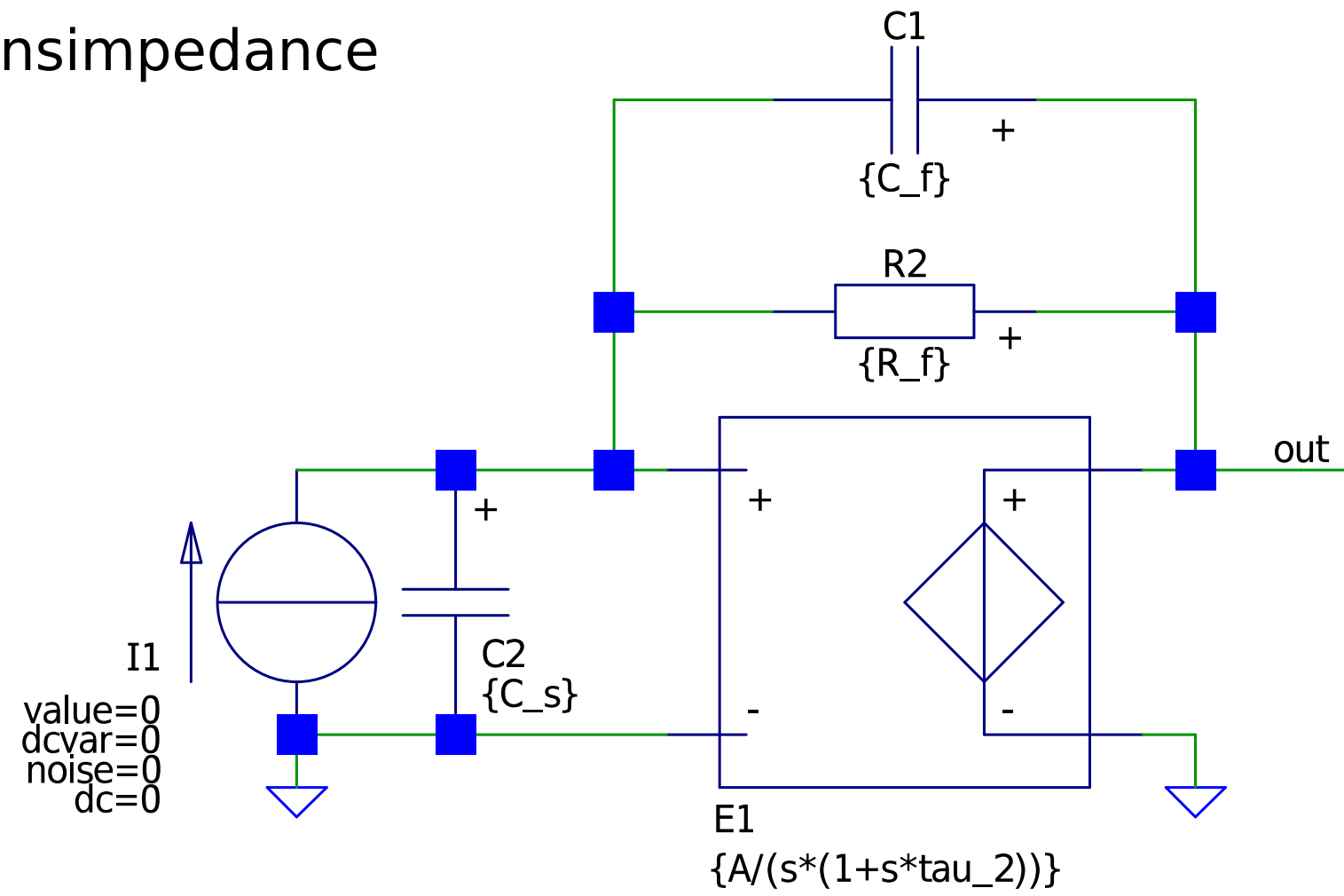
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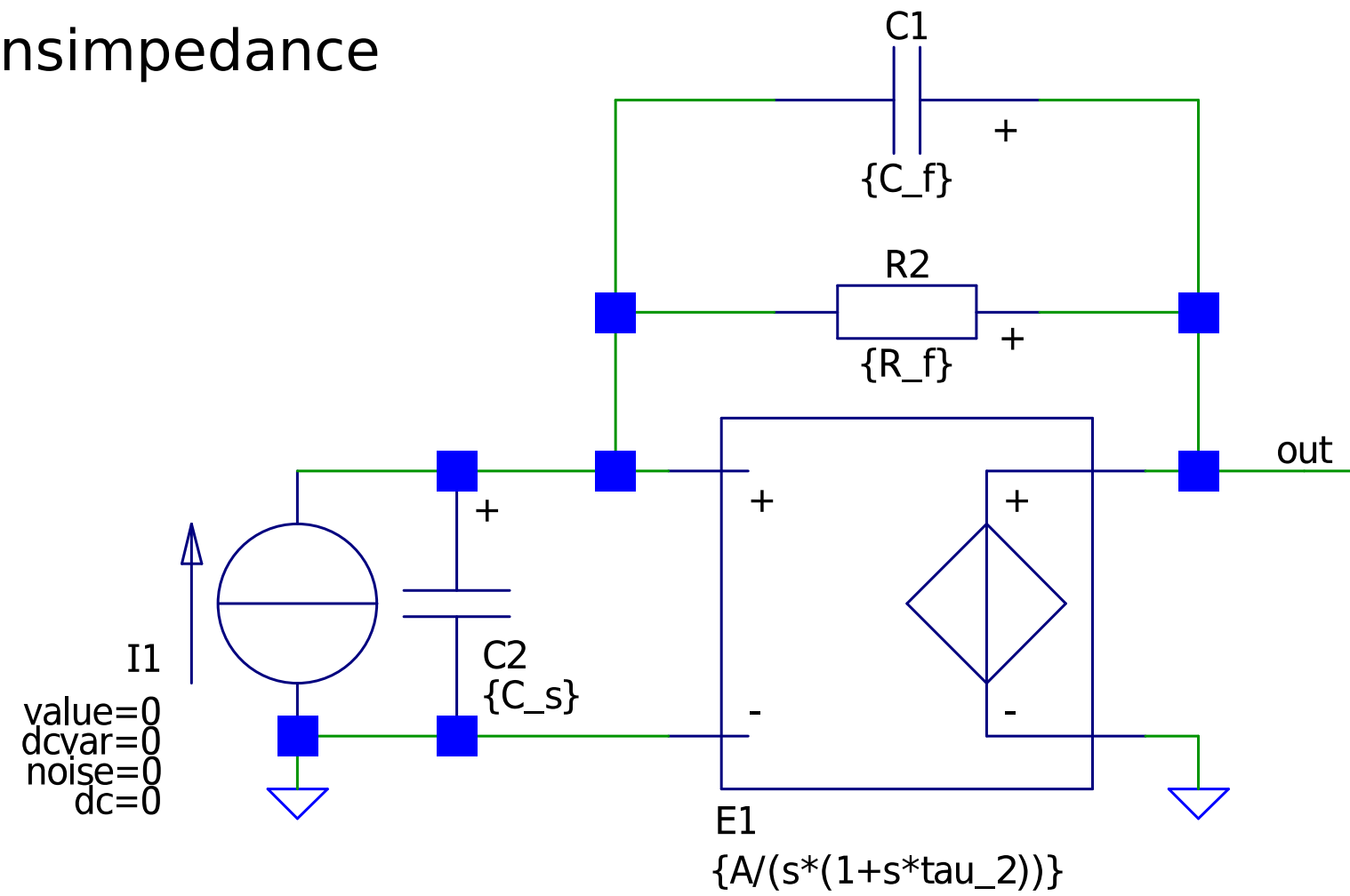
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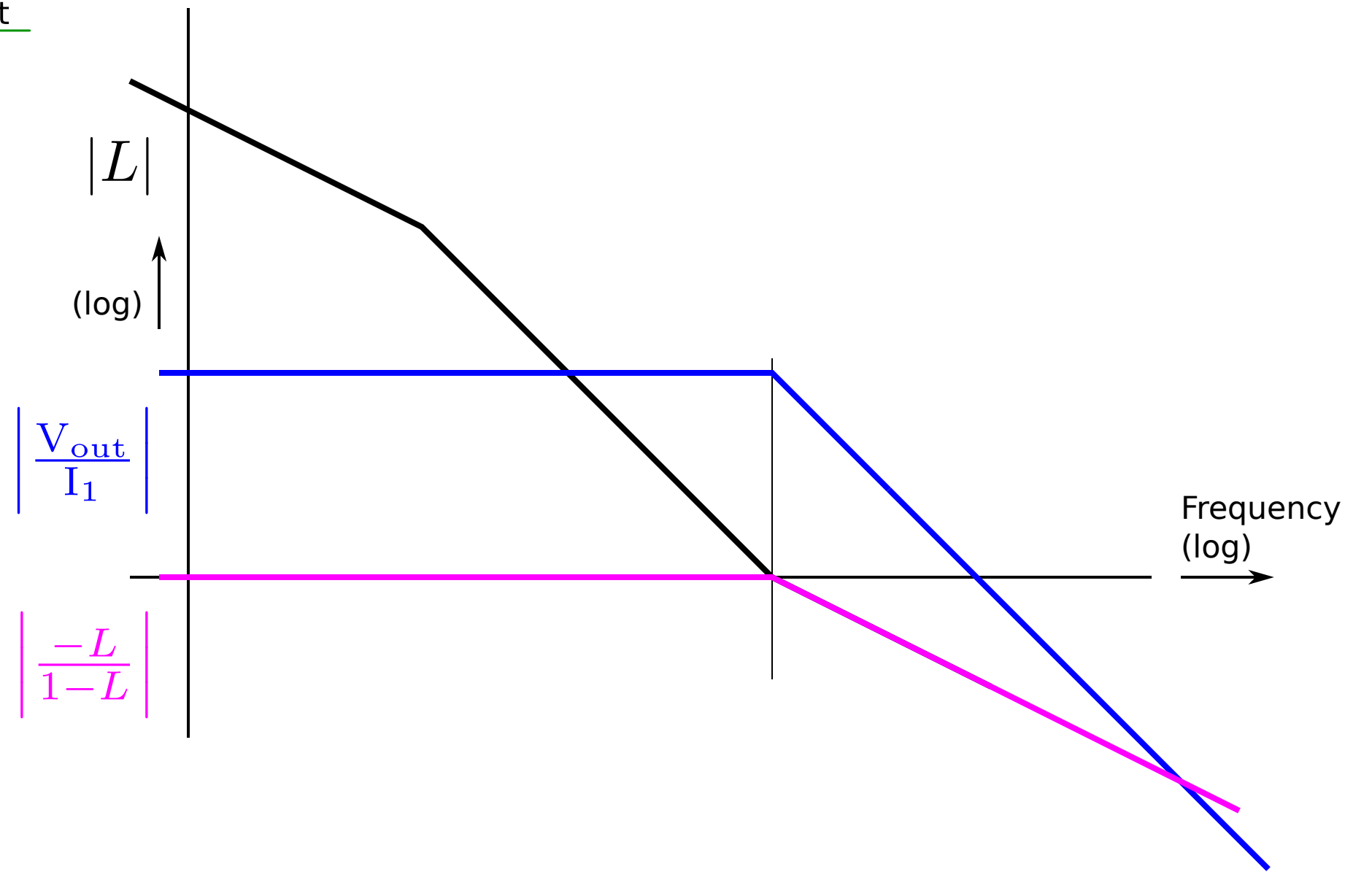
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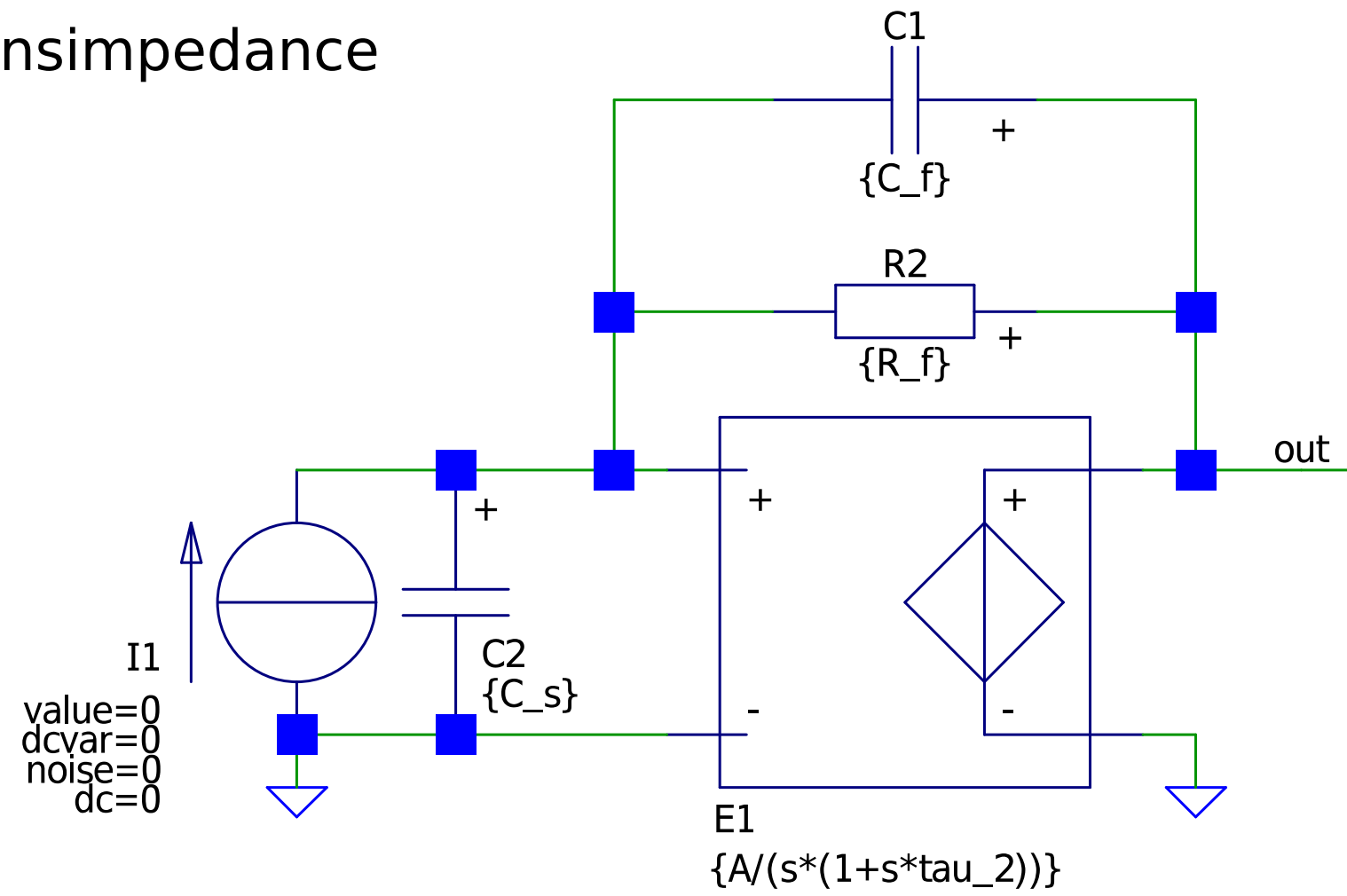
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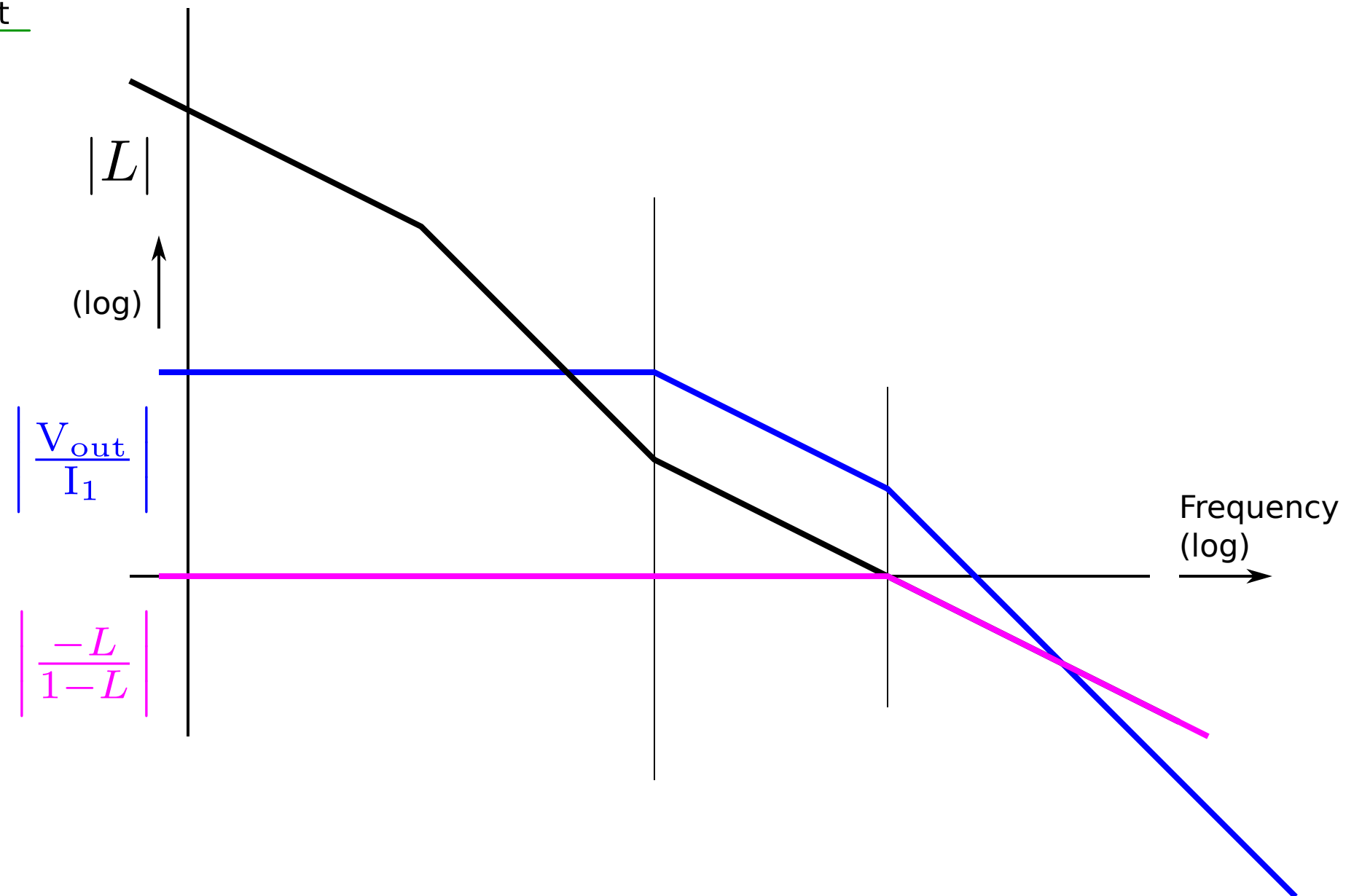
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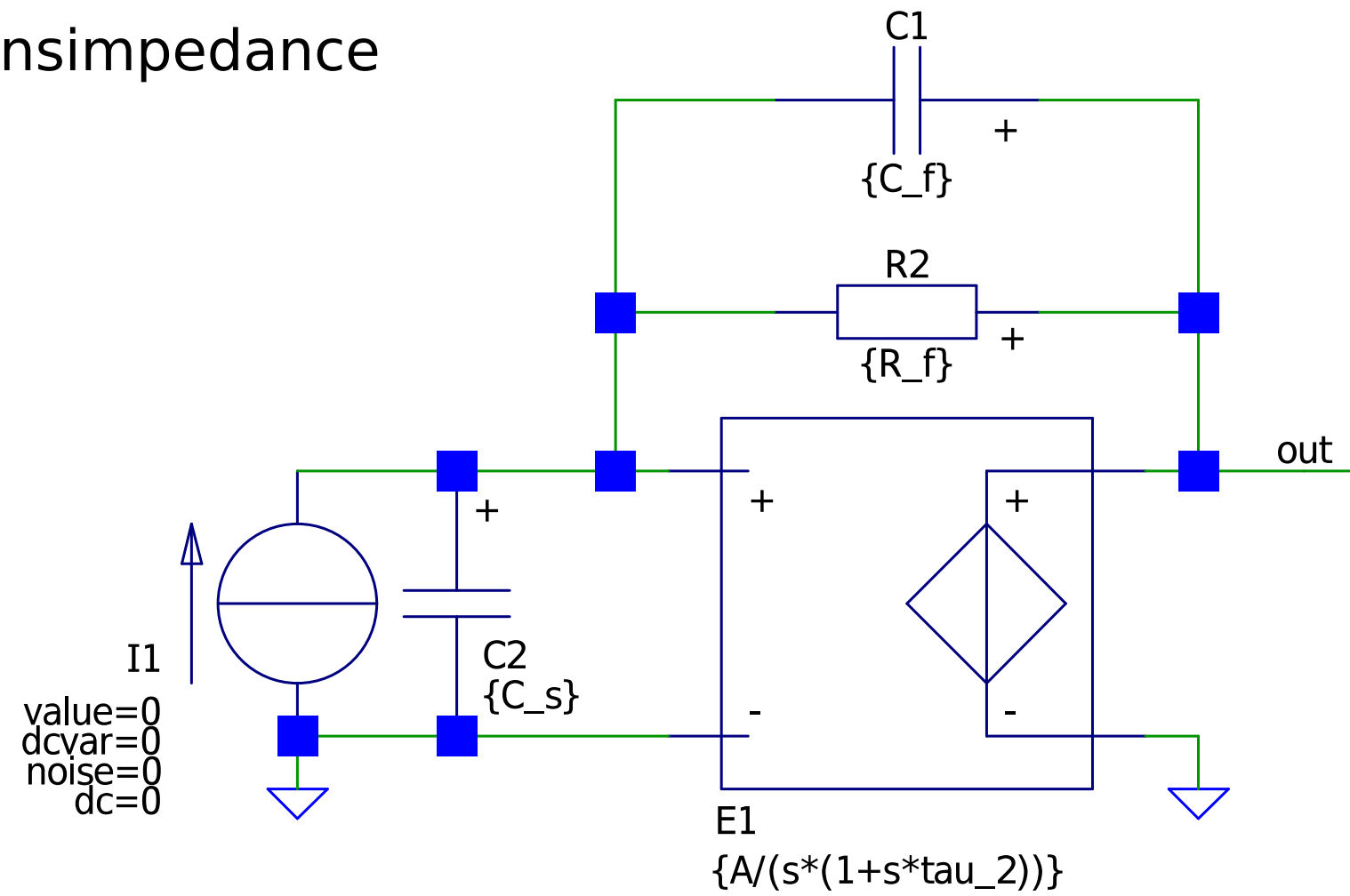
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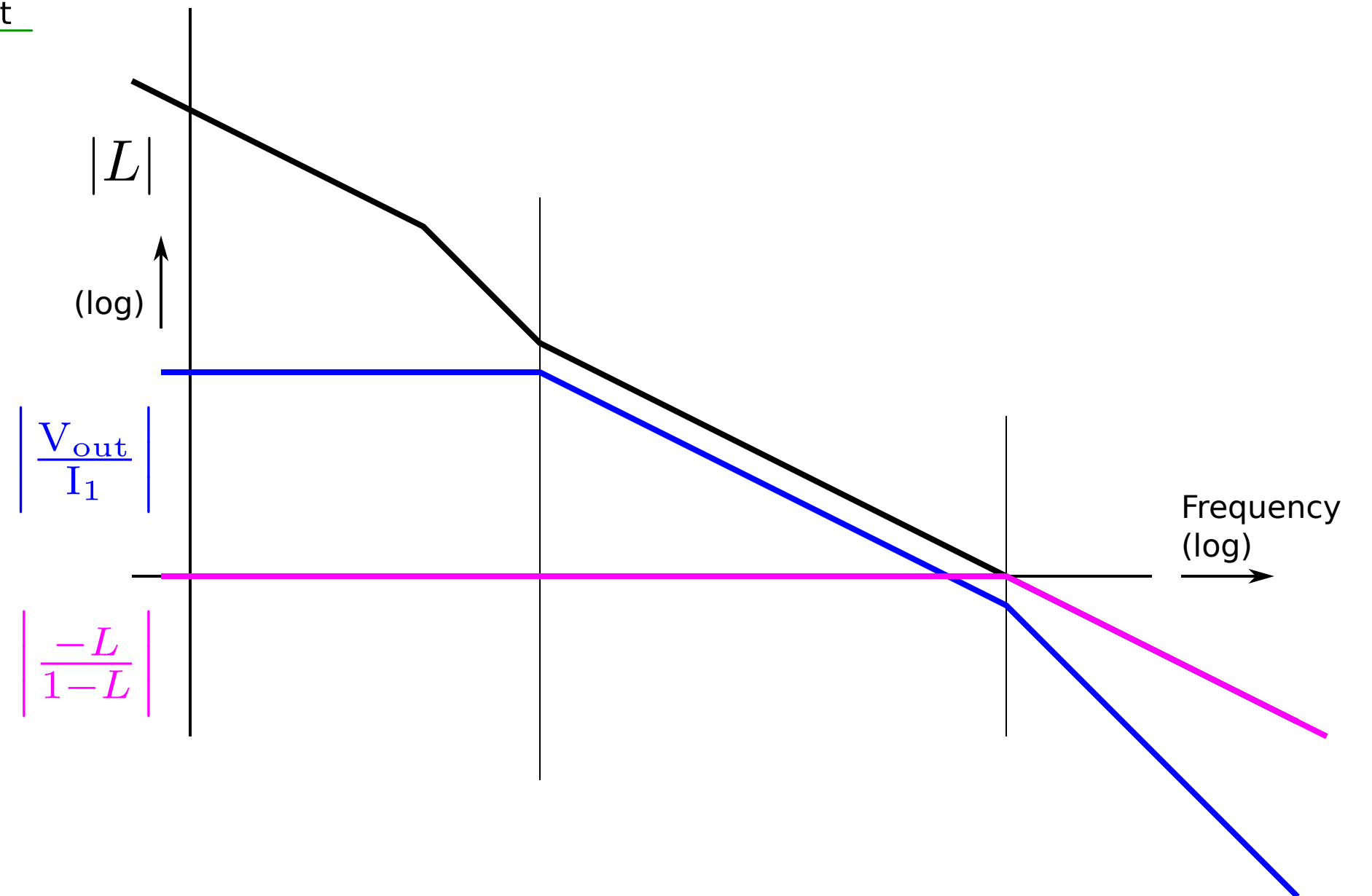
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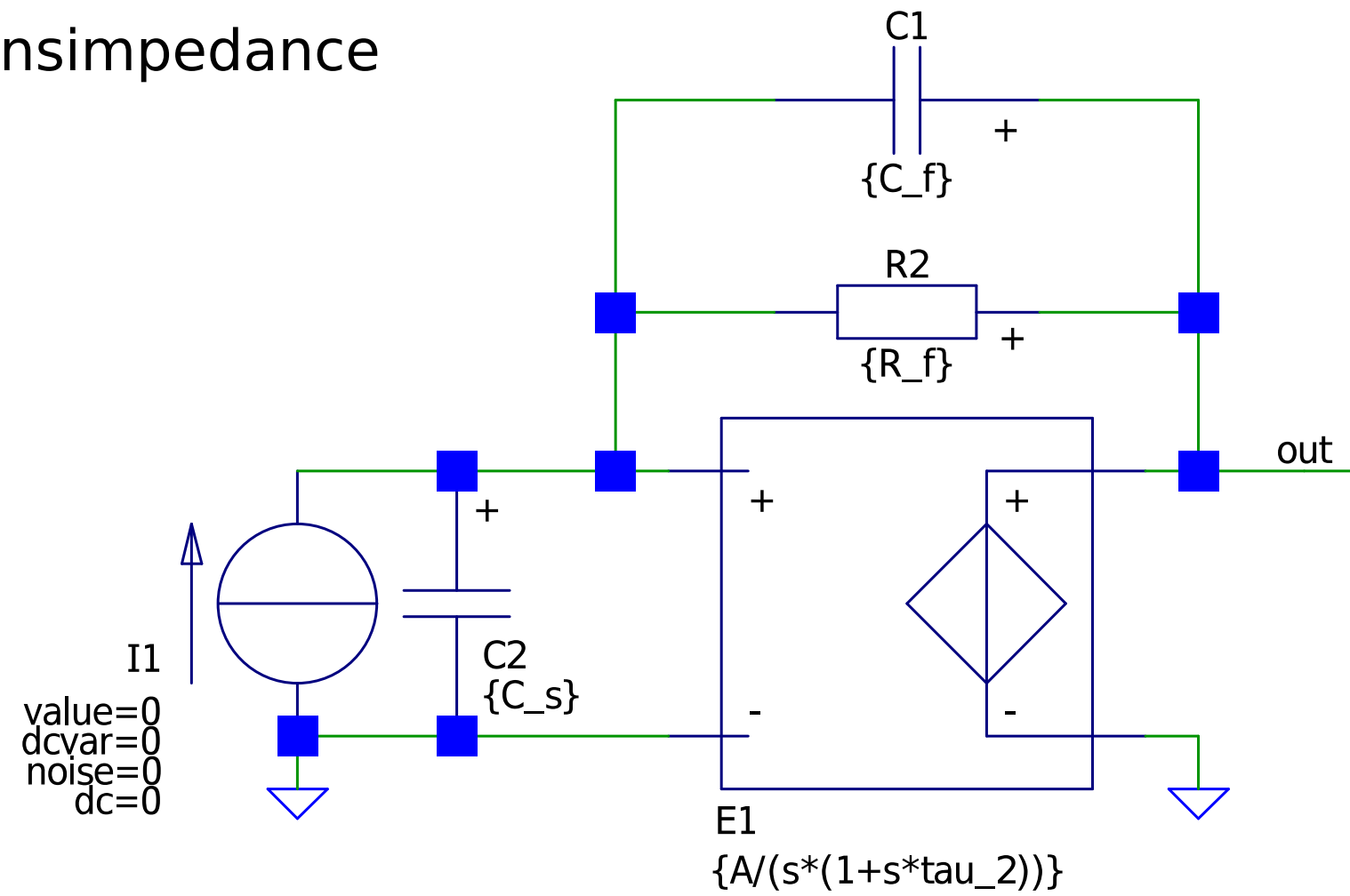
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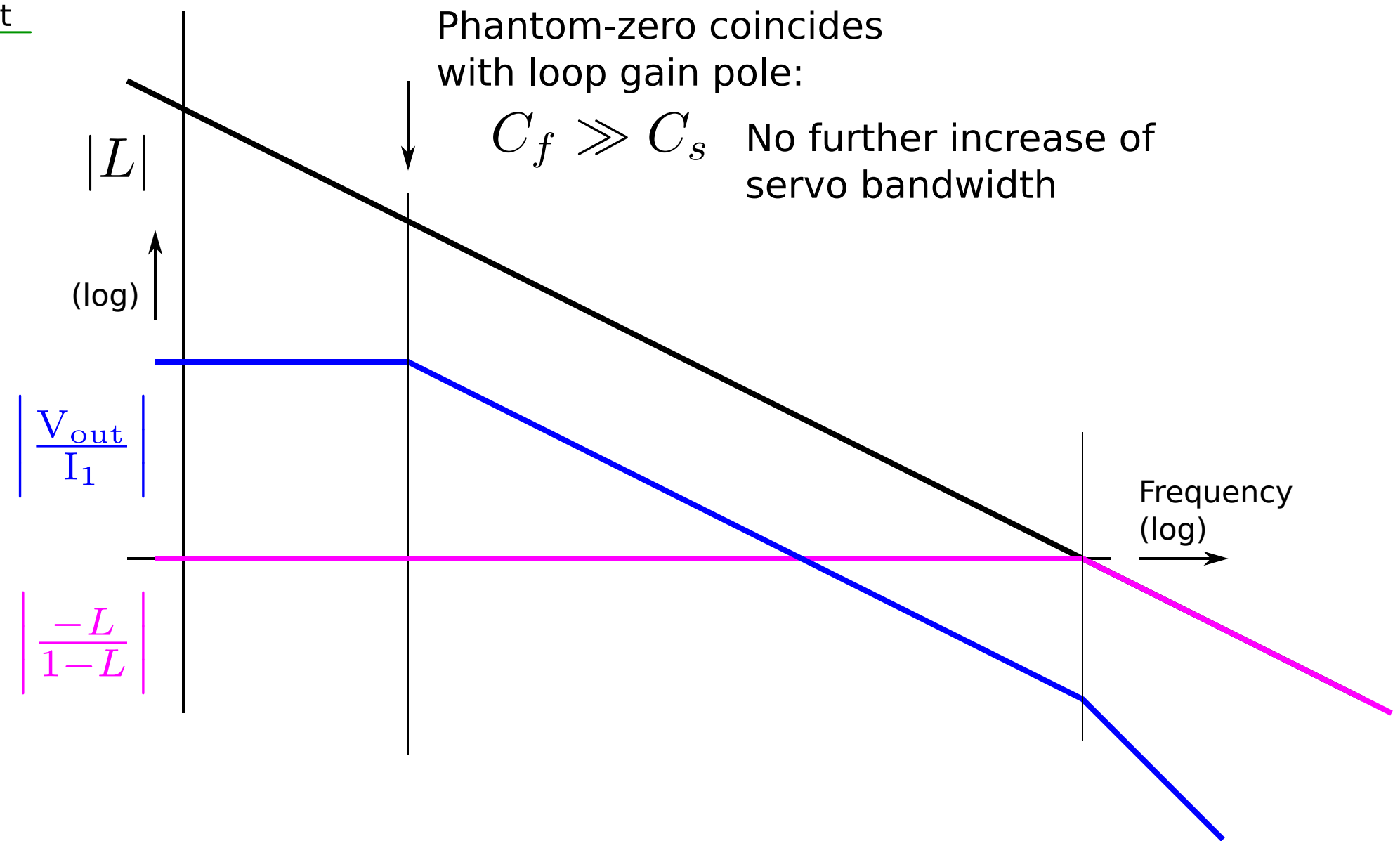
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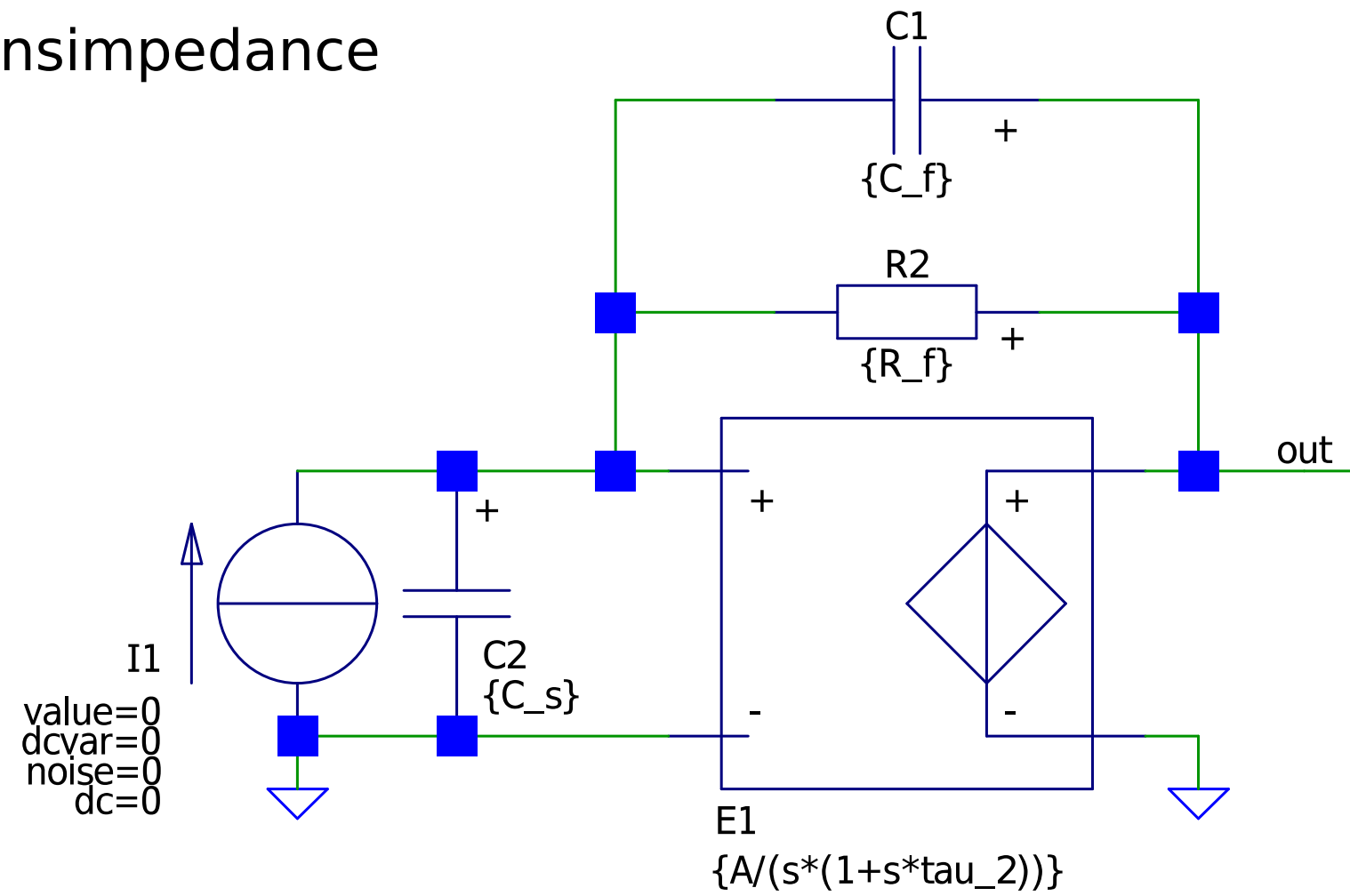
$$C_s = 300 \cdot 10^{12}$$

Reduction of product of the poles is not shown!



# Phantom zero bandwidth limitation

Transimpedance



$$C_f > 50 \cdot 10^{-12}$$

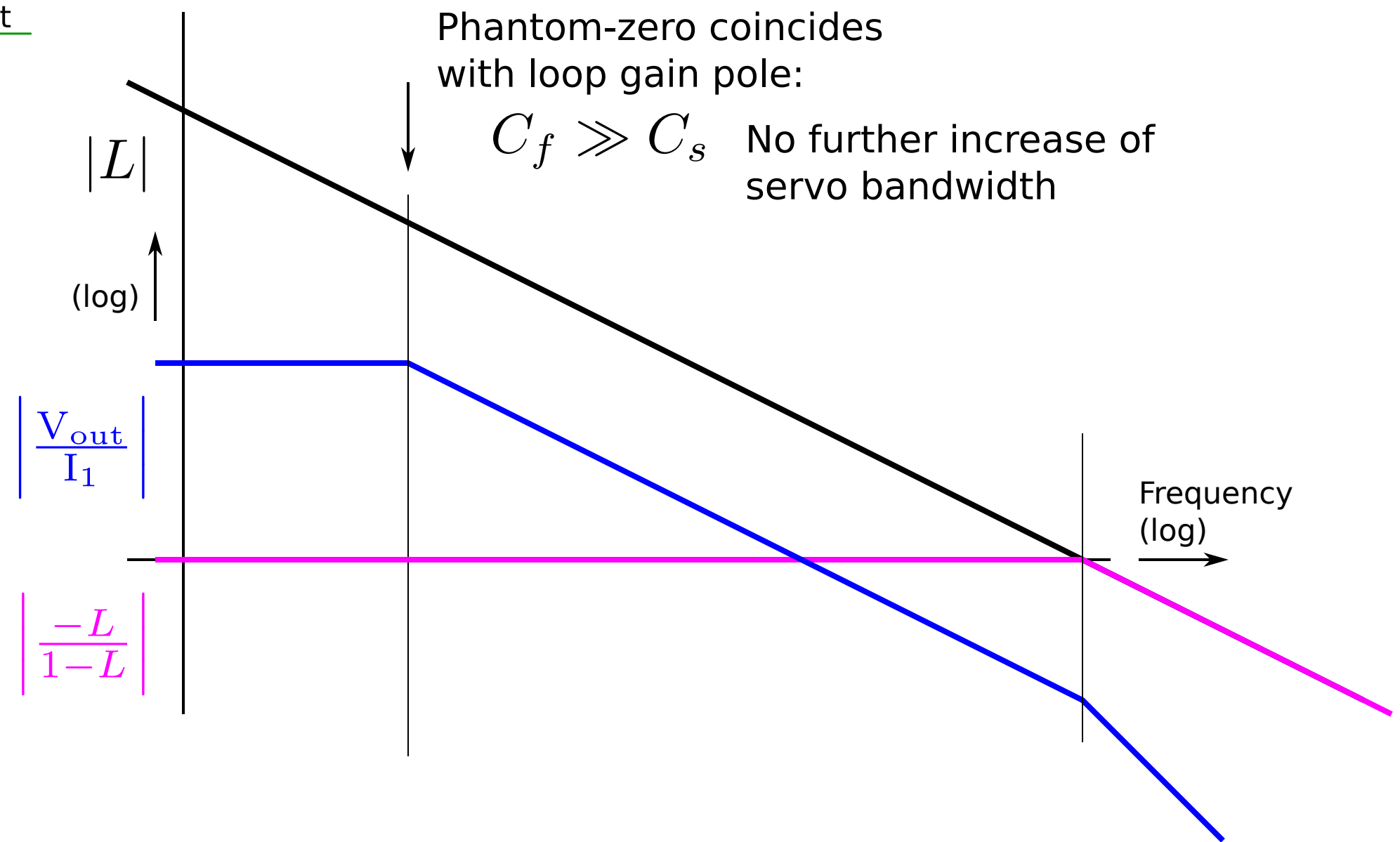
$$\tau_2 = 0$$

$$A = -10 \cdot 10^6$$

$$R_f = 10 \cdot 10^3$$

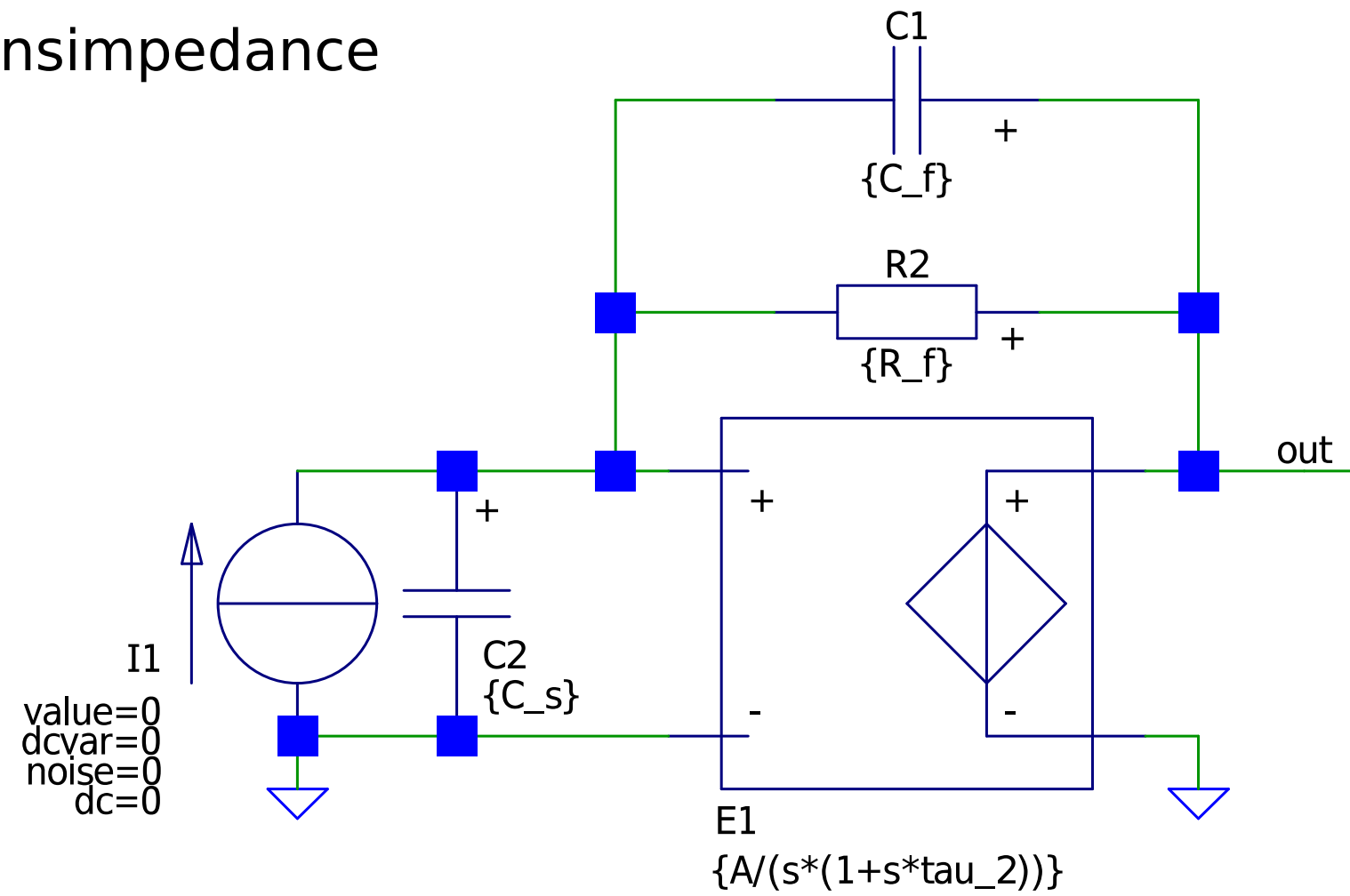
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# Phantom zero bandwidth limitation

Transimpedance



$$C_f > 50 \cdot 10^{-12}$$

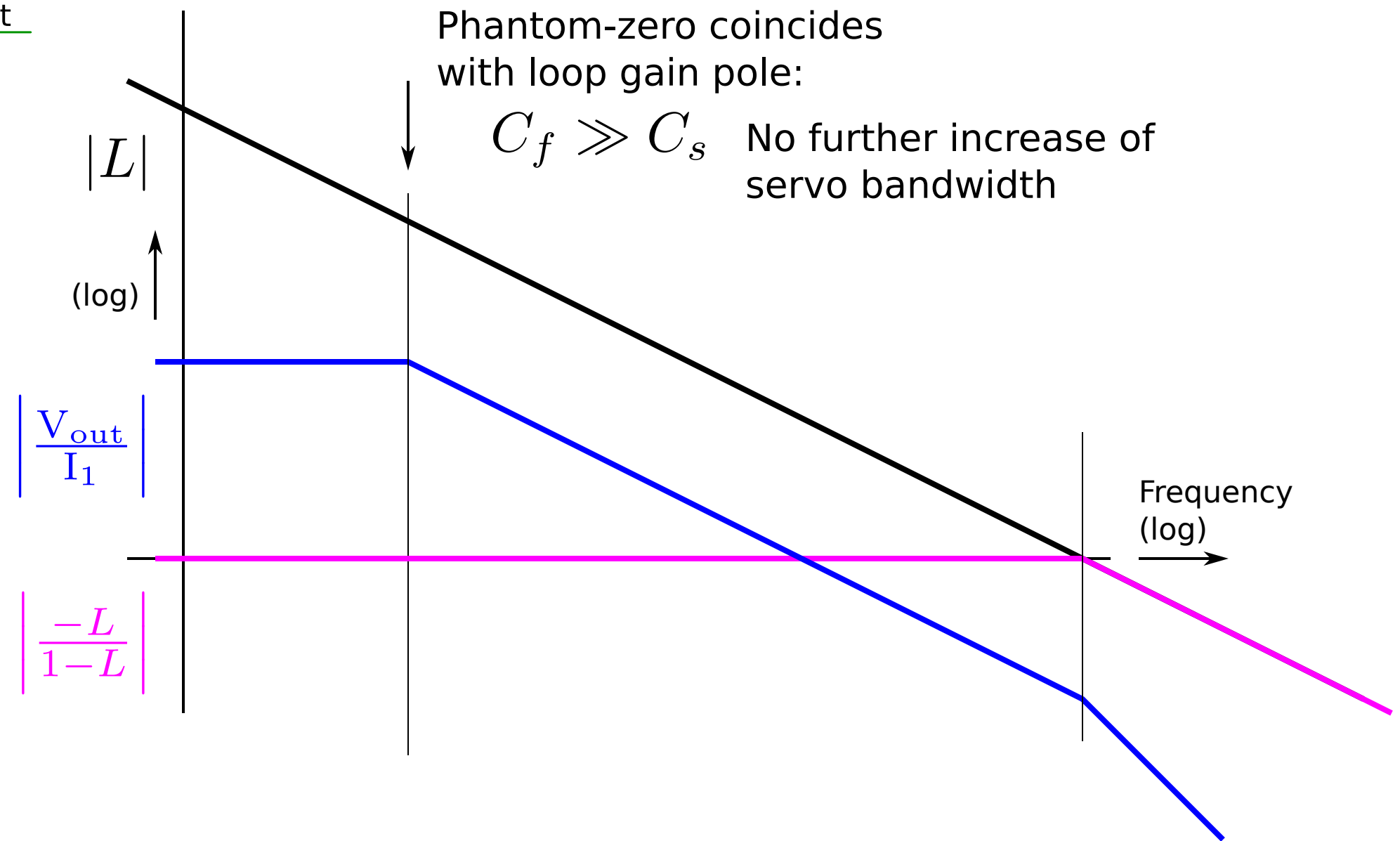
$$\tau_2 = 0$$

$$A = -10 \cdot 10^6$$

$$R_f = 10 \cdot 10^3$$

$$C_s = 300 \cdot 10^{12}$$

Reduction of product of the poles is not shown!

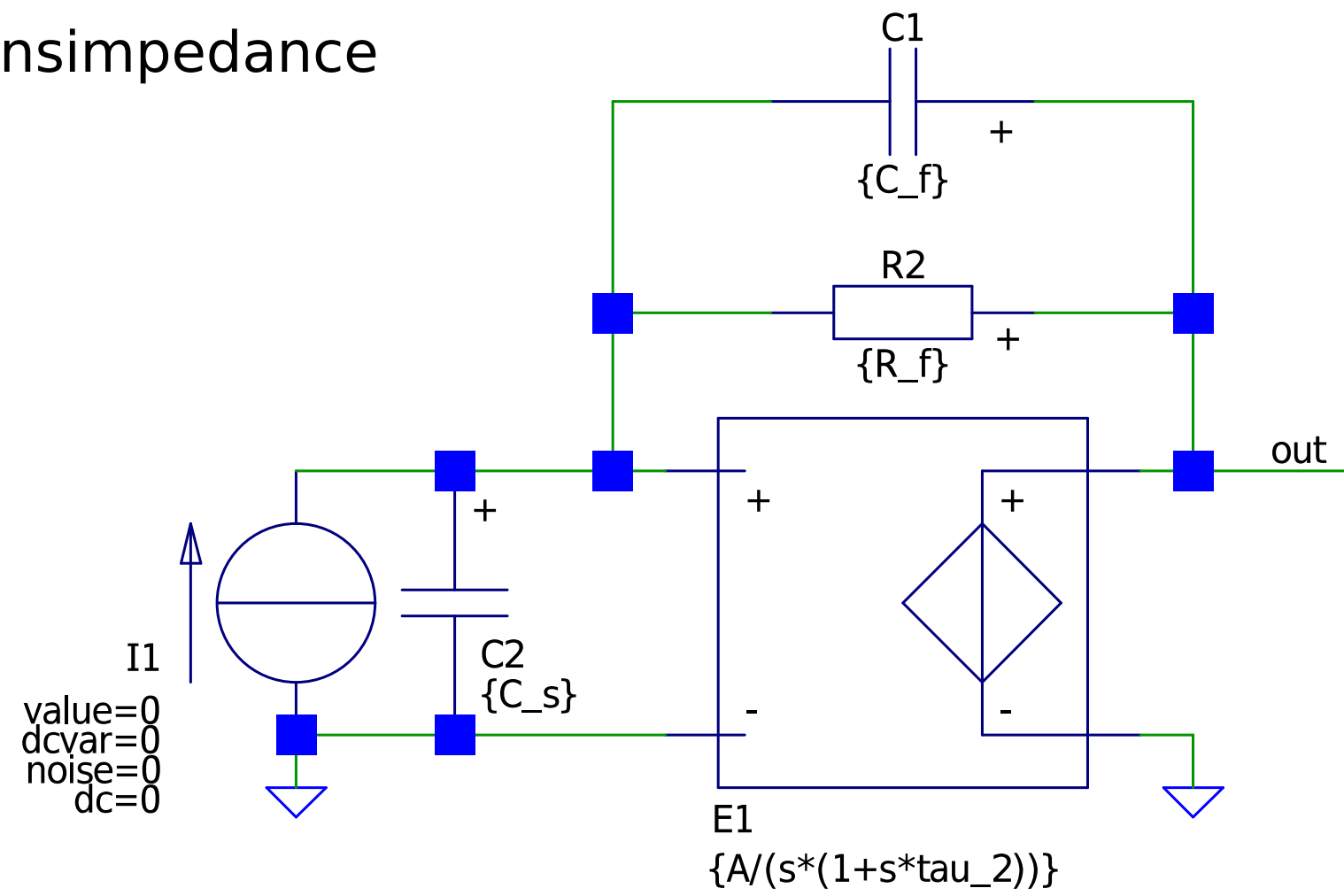


# Phantom zero bandwidth limitation



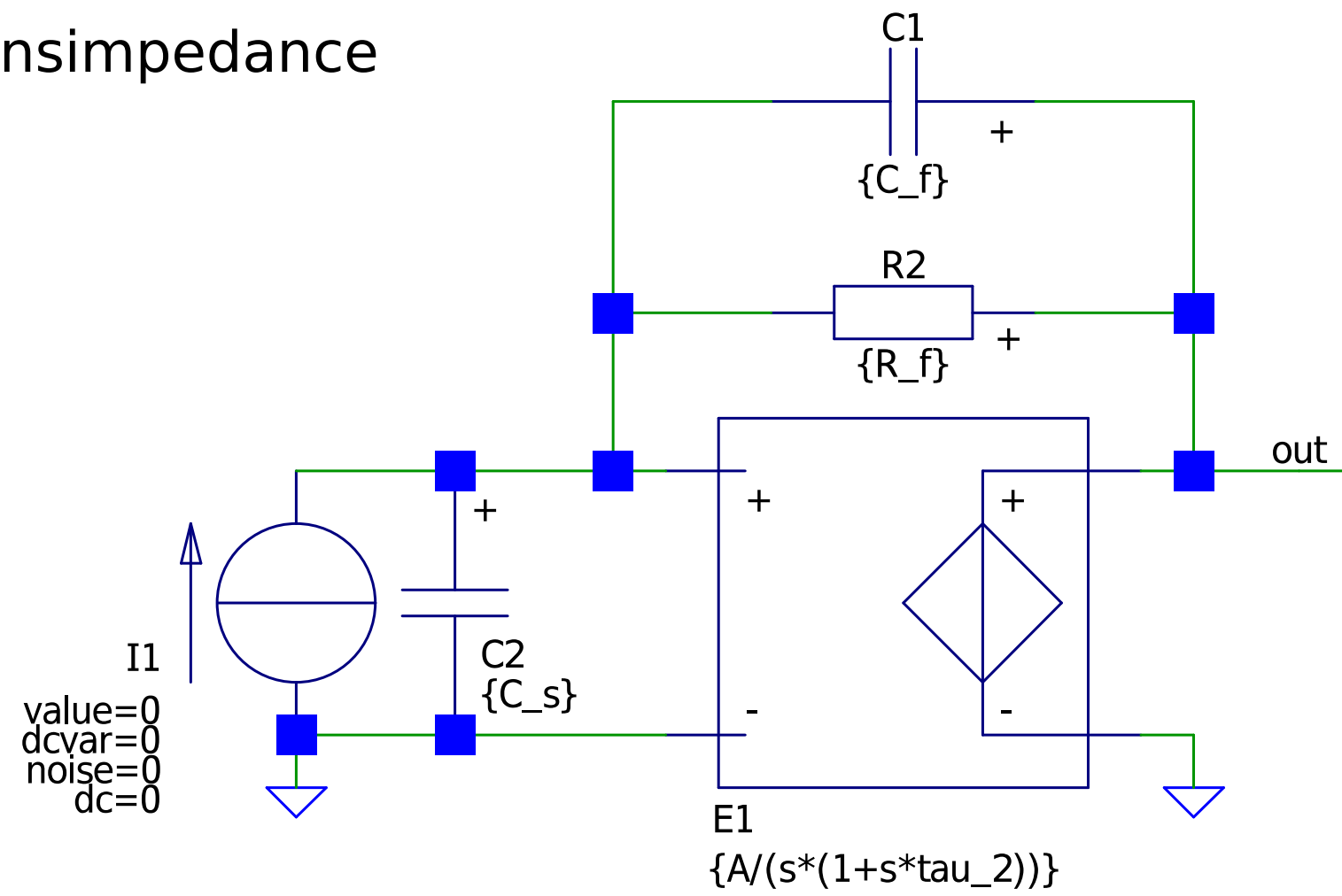
# Phantom zero bandwidth limitation

Transimpedance



# Phantom zero bandwidth limitation

Transimpedance



$$C_f > 50 \cdot 10^{-12}$$

$$\tau_2 > 0$$

$$A = -10 \cdot 10^6$$

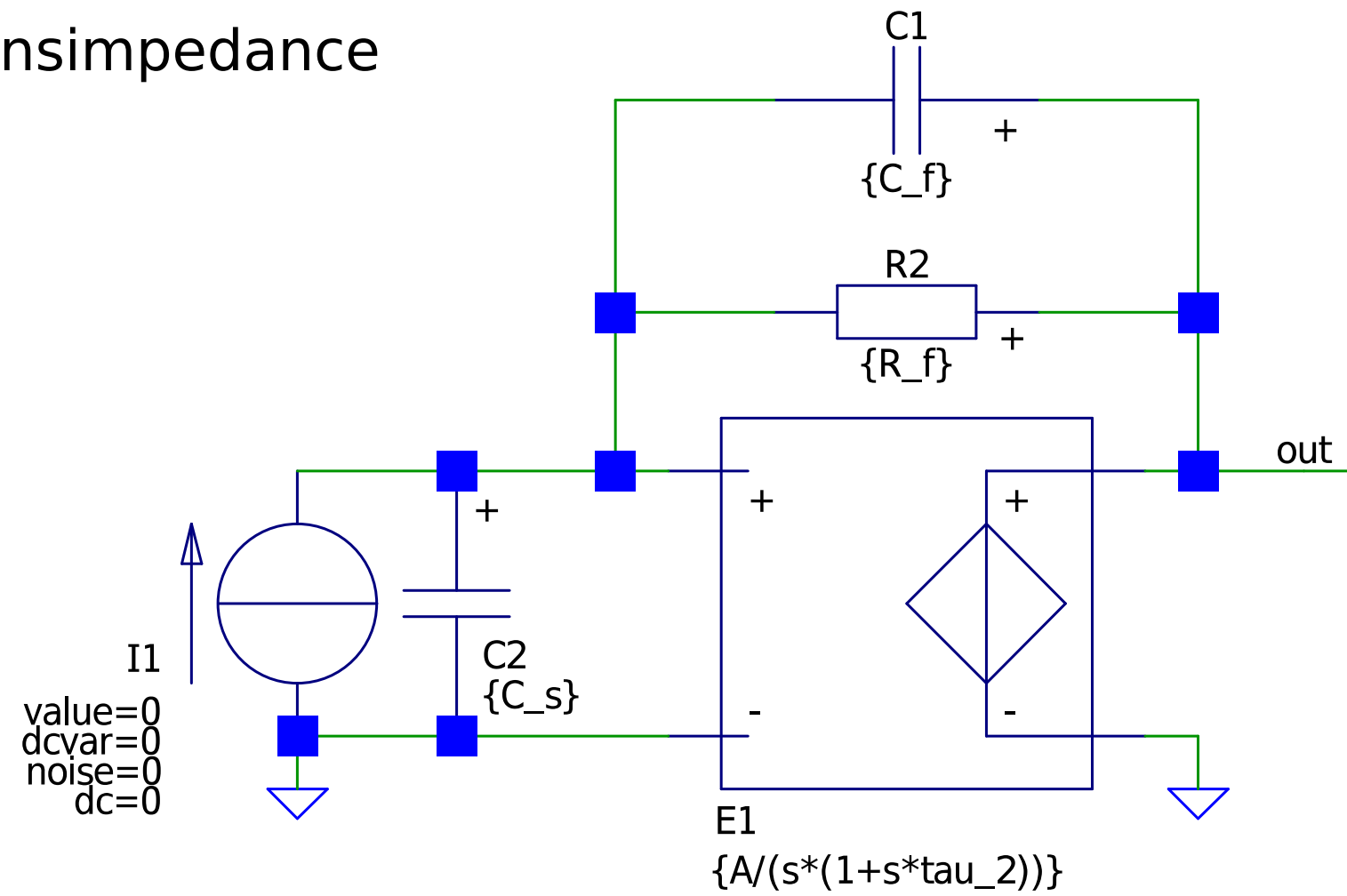
$$R_f = 10 \cdot 10^3$$

$$C_s = 300 \cdot 10^{12}$$

# Phantom zero bandwidth limitation

Transimpedance

Non-dominant poles may become dominant



$$C_f > 50 \cdot 10^{-12}$$

$$\tau_2 > 0$$

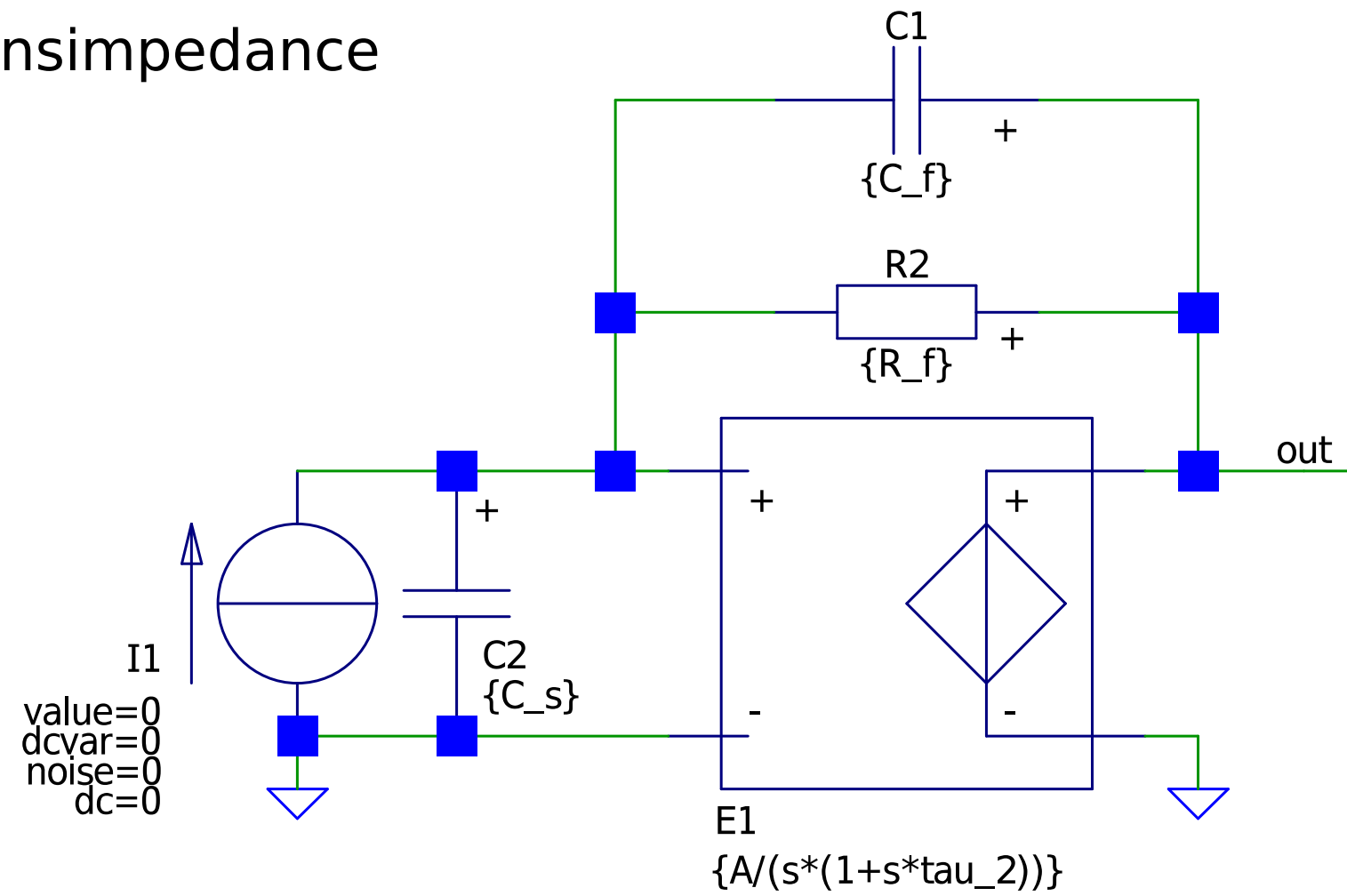
$$A = -10 \cdot 10^6$$

$$R_f = 10 \cdot 10^3$$

$$C_s = 300 \cdot 10^{12}$$

# Phantom zero bandwidth limitation

Transimpedance



Non-dominant poles may become dominant

Study effect in: [PhZbwLimit.py](#)

$$C_f > 50 \cdot 10^{-12}$$

$$\tau_2 > 0$$

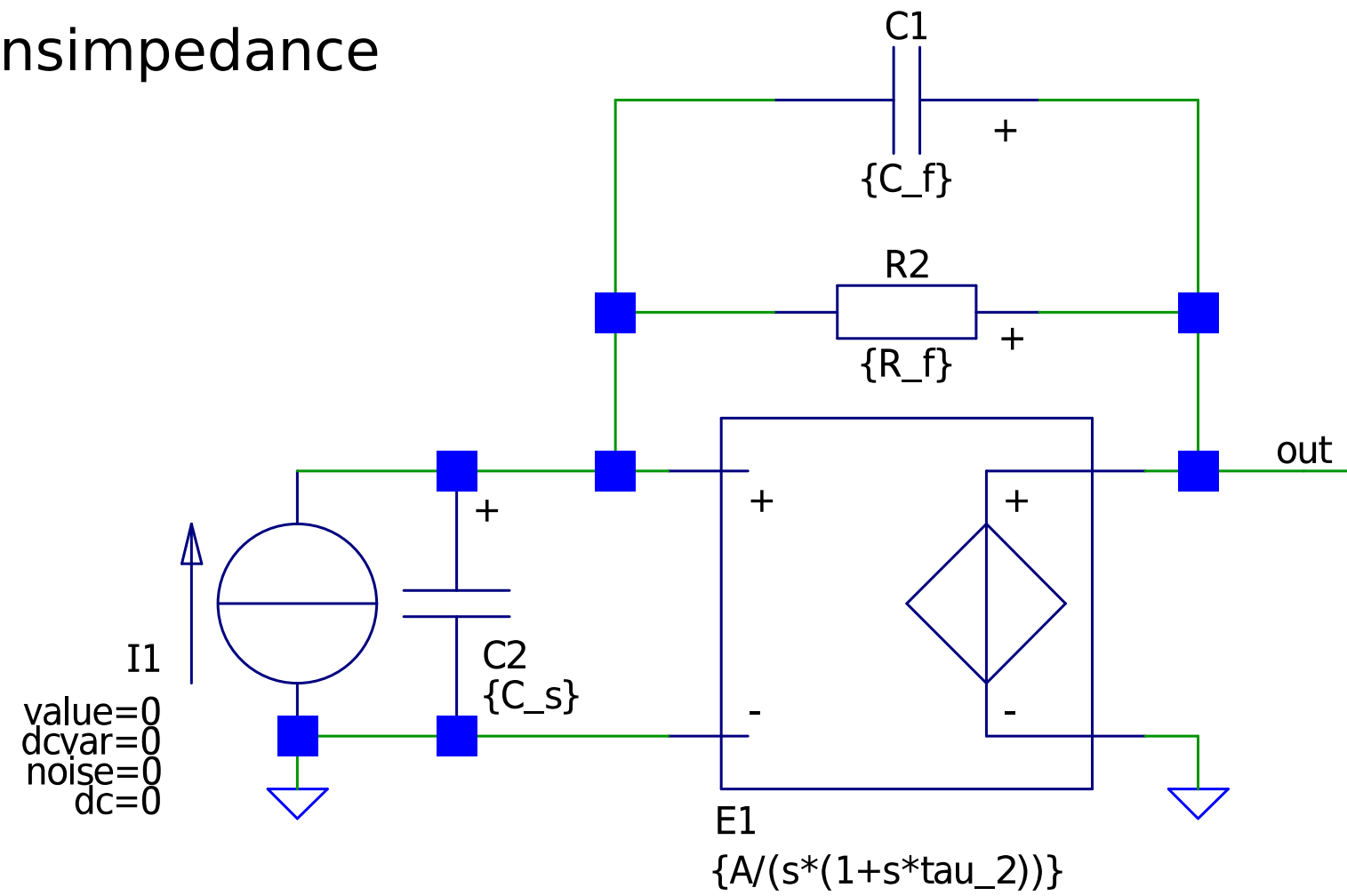
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$$R_f = 10 \cdot 10^3$$

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# Phantom zero bandwidth limitation

Transimpedance



Non-dominant poles may become dominant

Study effect in: PhZbwLimit.py

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$$R_f = 10 \cdot 10^3$$

$$C_s = 300 \cdot 10^{12}$$